

Representation of parameter uncertainty in probabilistic inflow models of SDDP

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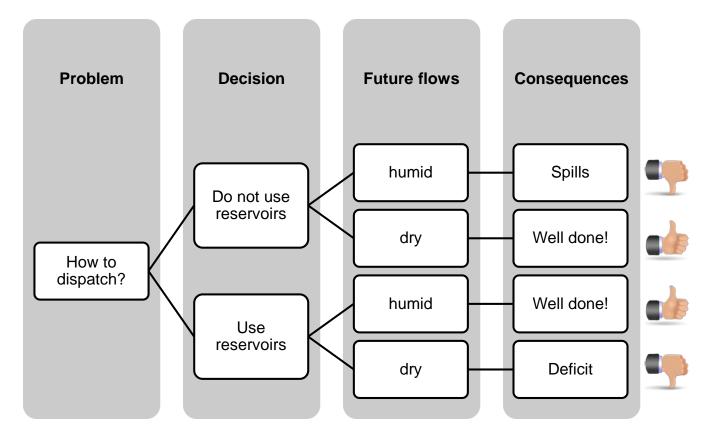
Objective

- Generation of inflow scenarios with parameter uncertainty
- Selection of best inflow model
- SDDP policy calculation with different inflow models
- Conclusions



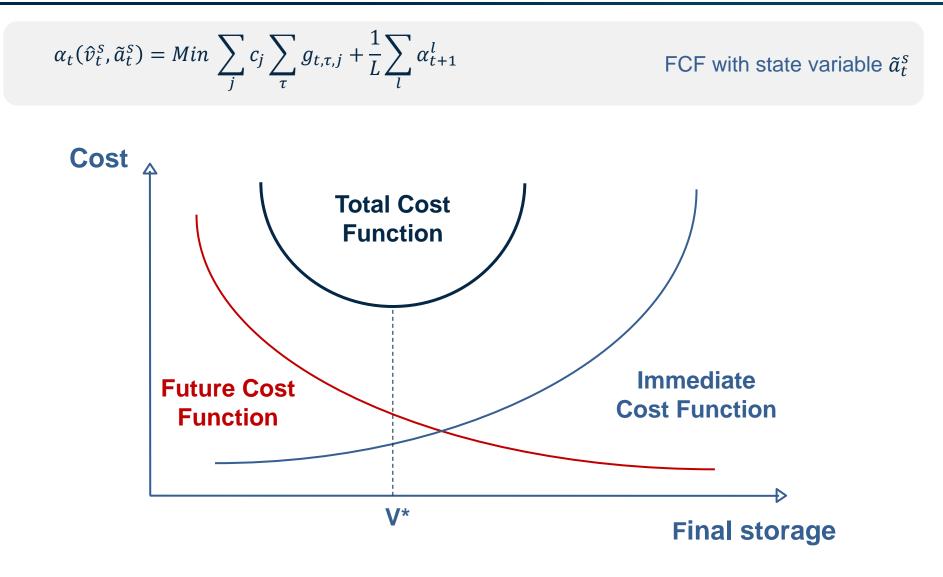
Hydrothermal dispatch p	The scheduling problem is solved by SDP or SDDP, where the original
Minimize present value of exp	problem is decomposed in one-stage sub-problems

Fuel costs + penalties for violation of operational constraints





Objective function: minimize total cost



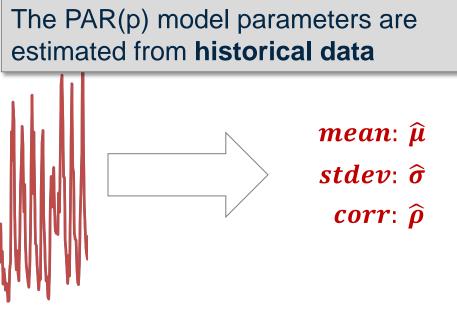


Parameter estimation

- Because it is impossible to have perfect forecasts of future inflows, uncertainty is represented through scenarios
 - Monte Carlo simulation
 based on PAR(p) models
 - Linearity of PAR(p) suitable for SDDP (convexity)

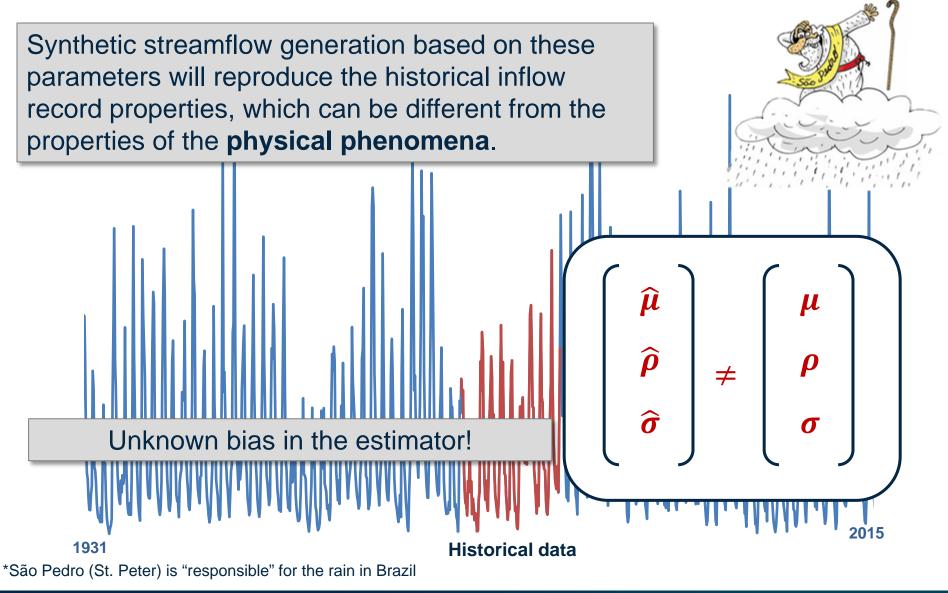


Hydro Furnas (1216 MW)



Historical data

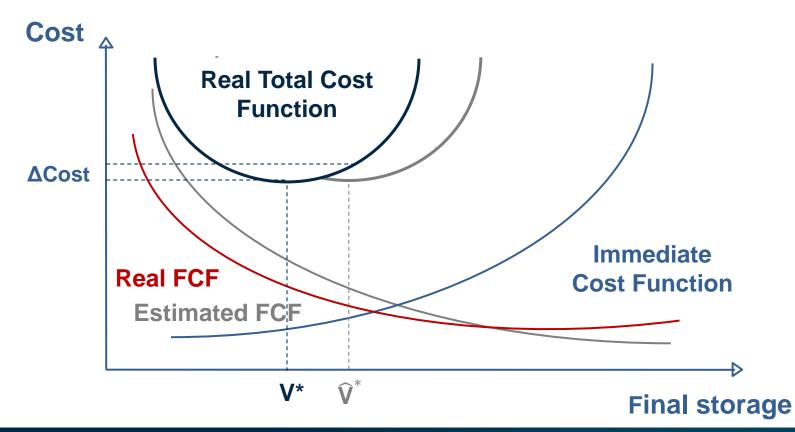
Does the historical record truly represents the physical inflow process?





Impact on operation policy: negative bias

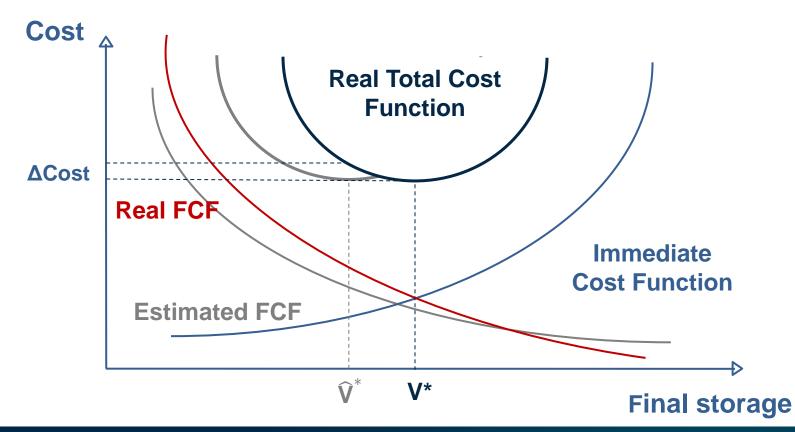
Water may be unnecessarily stored and is likely to be spilled in the future.





Impact on operation policy

Hydro reservoirs are depleted faster than needed, resulting in the dispatch of costly thermal plants in the future.

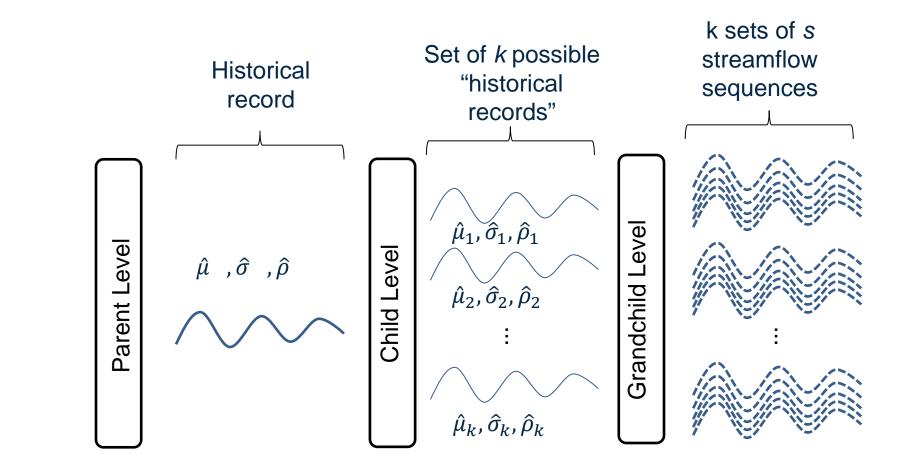




- Assess the impacts of incorporating the uncertainty of the PAR model parameters in the stochastic hydrothermal scheduling model.
- Develop a methodology to calculate a SDDP policy taking into account parameter uncertainty

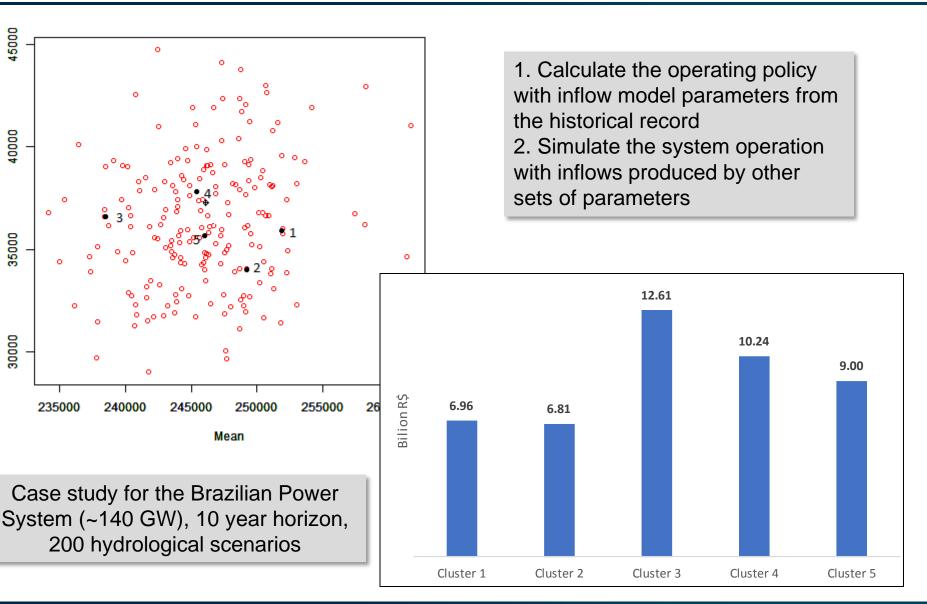


Generation of inflow scenarios with parameter uncertainty





Impact of parameter uncertainty on operation costs



PSR 🖉

Standard Deviation

Parameter estimation as part of stochastic optimization

- 1. Selection of inflow best model
- 2. SDDP policy calculation with different inflow models



1. Selection of best inflow model: key idea

- Calculate "taylor made" operating policies for each set of inflow model parameters m = 1, ..., M; simulate system operation with inflows produced by all the other parameters
- Decision criteria:
 - Expected value: $m^* = \underset{m}{\operatorname{argmin}} \sum_n p_n \tilde{z}_{mn}$

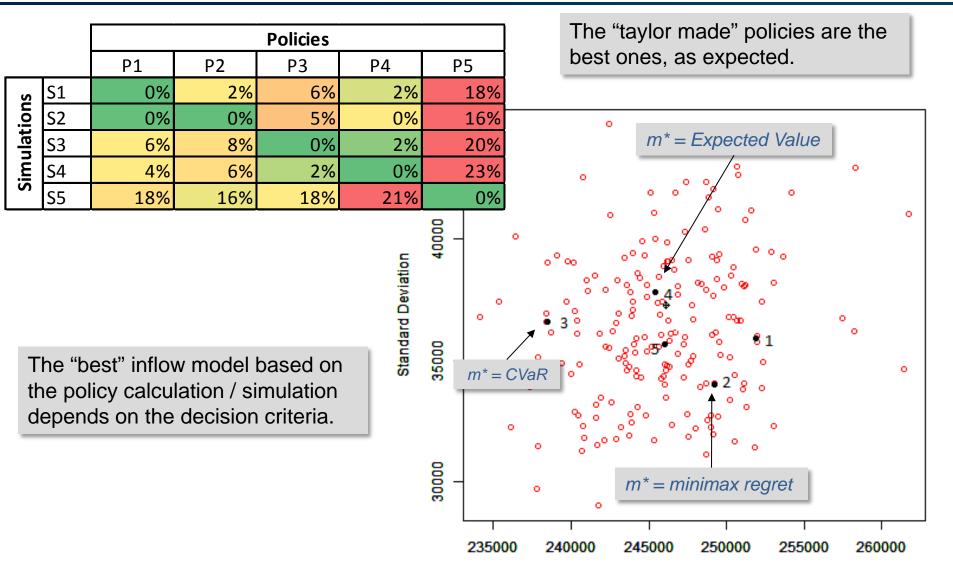
• Minimax regret: $m^* = \underset{m}{\operatorname{argmin}} \underset{n}{\operatorname{Max}} \{ \tilde{z}_{mn} - \tilde{z}_{mm} \}$

• Convex combination:
$$m^* = \underset{m}{\operatorname{argmin}} \left[\lambda \sum_n p_n \tilde{z}_{mn} + (1 - \lambda) \underset{n}{\operatorname{Max}} \{ \tilde{z}_{mn} - \tilde{z}_{mm} \} \right]$$

• CVaR:
$$m^* = \underset{m}{\operatorname{argmin}} [\lambda \sum_n p_n \tilde{z}_{mn} + (1 - \lambda) CVaR_q \{\tilde{z}_{mn}\}]$$



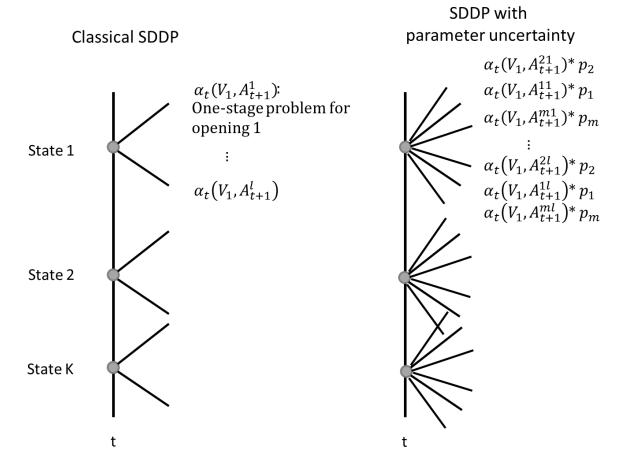
1. Selection of best inflow model: case study





2. SDDP policy with different inflow models: key idea

Represent all the *M* alternative inflow models as part of the SDDP recursion





2. SDDP policy with different inflow models: formulation

▶ \mathcal{M} PAR(1) models with probabilities { p_m , $m = 1, ..., \mathcal{M}$ }

$$\alpha_t(\hat{v}_t^s, \tilde{a}_t^s) = Min \sum_j c_j \sum_{\tau} g_{t,\tau,j} + \sum_m p_m \left[\frac{1}{L} \sum_l \alpha_{t+1}^{ml}\right]$$
 FCF with state variable \tilde{a}_t^s

$$v_{t+1,i} = \hat{v}_{t,i}^{s} + \tilde{a}_{t,i}^{s} - (u_{t,i} + s_{t,i}) + \sum_{\eta \in M_i} (u_{t,\eta} + s_{t,\eta})$$
 water balance

 $\sum_{i} e_{t,\tau,i} + \sum_{j} g_{t,\tau,j} = \hat{d}_{t,\tau} - \sum_{n} \hat{r}_{t,\tau,n}^{s}$ demand balance

$$\frac{\left(a_{t+1,i}^{ml} - \hat{\mu}_{w(t+1),i}^{m}\right)}{\hat{\sigma}_{w(t+1),i}^{m}} = \hat{\rho}_{w(t),i}^{m} \times \frac{\left(\tilde{a}_{t,i}^{s} - \hat{\mu}_{w(t),i}^{m}\right)}{\hat{\sigma}_{w(t+1),i}^{m}} + \sqrt{1 - \left[\hat{\rho}_{w(t),i}^{m}\right]^{2}} \times \hat{\xi}_{t,i}^{l} \quad \forall i, l, m \quad \text{stochastic model}$$

$$\alpha_{t+1}^{ml} \ge \sum_{i} \hat{\varphi}_{ht+1,i}^{\mathcal{P}} \times v_{t+1,i} + \sum_{i} \hat{\varphi}_{at+1,i}^{\mathcal{P}} \times a_{t+1,i}^{ml} + \hat{\varphi}_{0t+1}^{\mathcal{P}} \quad \forall \mathcal{P}, m, l \quad \text{Benders cuts}$$



2. SDDP policy with different inflow models: case study

- Test system with 1 hydro and 3 thermal plants
- 12 month study period; 4096 hydrological scenarios

		Final Simulation				
		Cluster 1	Cluster 2	Cluster 3	Cluster 4	Cluster 5
Policy	Ω_1 Cluster 1	0.0%	0.2%	2.3%	1.2%	2.1%
	Ω_2 Cluster 2	0.6%	0.0%	2.2%	1.2%	2.1%
	Ω_3 Cluster 3	1.1%	0.8%	0.0%	0.5%	0.8%
	Ω_4 Cluster 4	34.5%	29.1%	50.8%	0.0%	81.4%
	Ω_5 Cluster 5	0.9%	1.1%	0.4%	0.4%	0.0%
	Ω_6 Parameter Uncertainty	0.6%	0.4%	0.0%	0.2%	0.5%

The policy with parameter uncertainty minimizes both expected operation cost and maximum regret

And there are more improvements!

► The policy can be refined by using the probability of each model *conditioned* to the current inflow value $\tilde{a}_{t,i}^{s}$.

$$\alpha_t \left(\hat{v}_t^s, \tilde{a}_t^s, \mathcal{C}_t^{\mathscr{K}(s)} \right) = Min \sum_j c_j \sum_{\tau} g_{t,\tau,j} + \sum_{\nu} p_t^{\mathscr{K}\nu} \left[\sum_m p_{tm}^{\mathscr{K}} \left(\frac{1}{L} \sum_l \alpha_{t+1}^{ml\nu} \right) \right]$$

inflow cluster as state variable

- For each cluster C_t^{k} there is an associated vector of model probabilities $\{p_{tm}^{k}\}$
- ► The transition probability from cluster k in stage t to cluster v in stage t + 1 is p_t^{kv} .



- Parameter uncertainty has a significant impact on system operating costs
- The representation of uncertainty in the operating policy minimized both expected operation cost and maximum regret
- The quality of the proposed policy can be improved by modeling the inflows as a Markov Chain, with transition probabilities between each cluster.



References

- B. Bezerra; A. Veiga Filho; L. A. Barroso; M. Pereira, "Stochastic Long-term Hydrothermal Scheduling with Parameter Uncertainty in Autoregressive Streamflow Models," in *IEEE Transactions on Power Systems*, 2016
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Questions?

