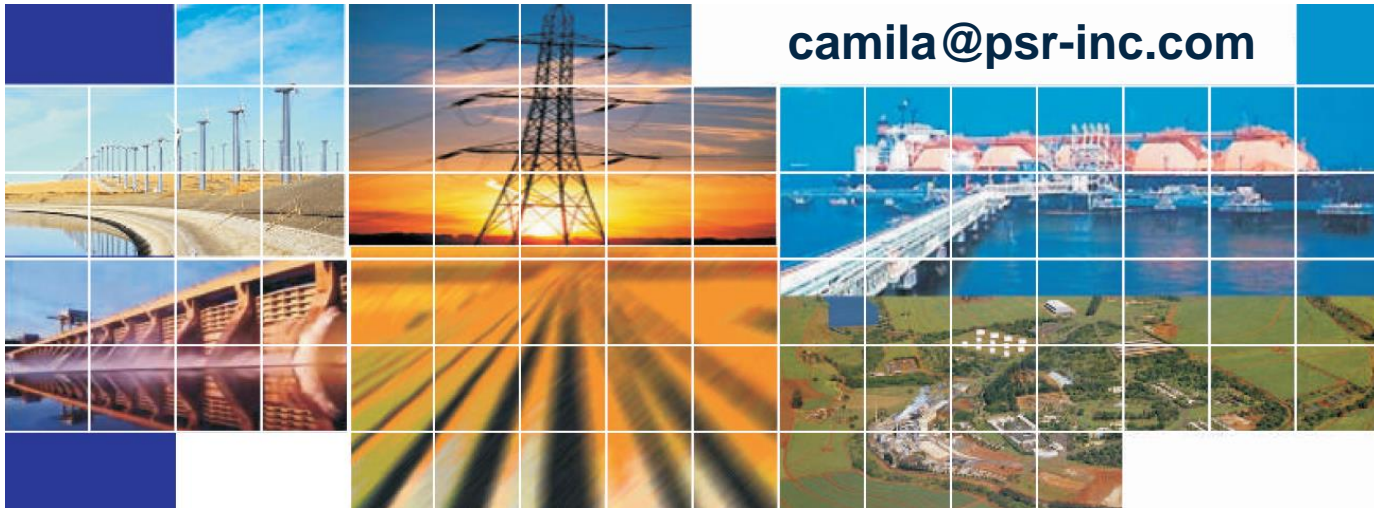


## IMMEDIATE COST FUNCTION

Camila Metello

[camila@psr-inc.com](mailto:camila@psr-inc.com)



ICSP

June 2016



# Outline

---

- ▶ Introduction
- ▶ SDDP
- ▶ Basic concepts
- ▶ Immediate cost function calculation method
- ▶ Results
- ▶ Final conclusions

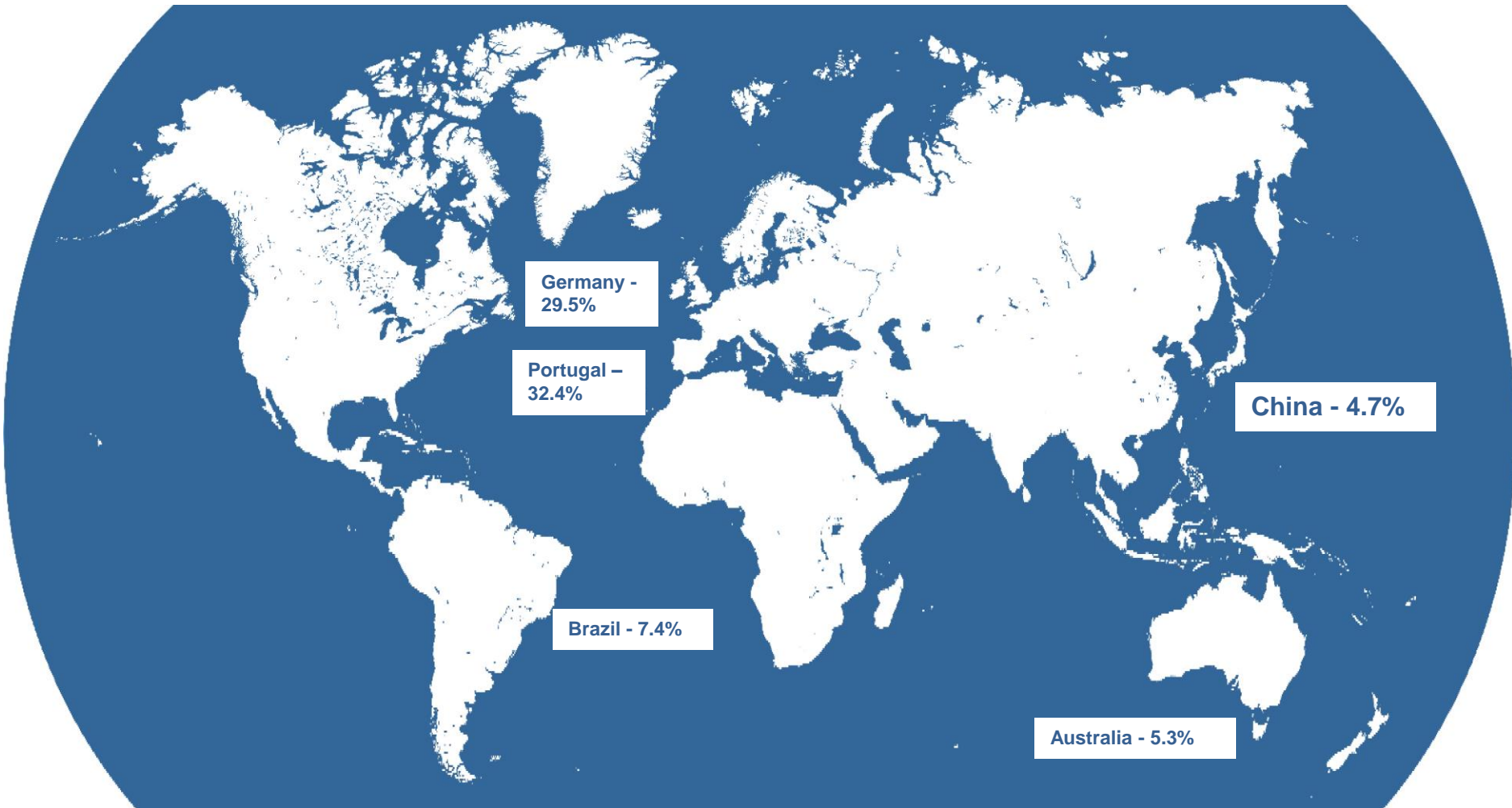
# Outline

---

- ▶ Introduction
- ▶ SDDP
- ▶ Basic concepts
- ▶ Immediate cost function calculation method
- ▶ Results
- ▶ Final conclusions

# Introduction

- Non-hydro renewable generation in energy markets:



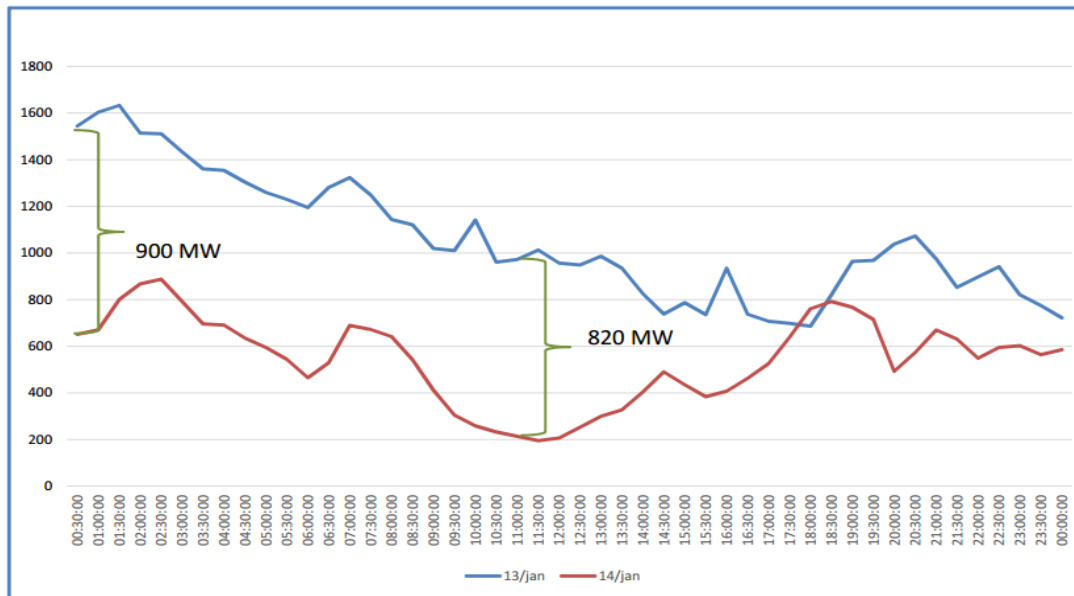
# Introduction

---

- ▶ Renewable generation penetration in energy markets:
  - In Brazil:
    - 3% of total generation capacity is Wind power
    - Great solar generation potential
  - All over the world:
    - In 2015, over 60 GW of wind generation sources were installed in the world, half of this capacity in China
    - In Germany, the goal is to have renewable generation responsible for 80% of total yearly energy generation in 2050.

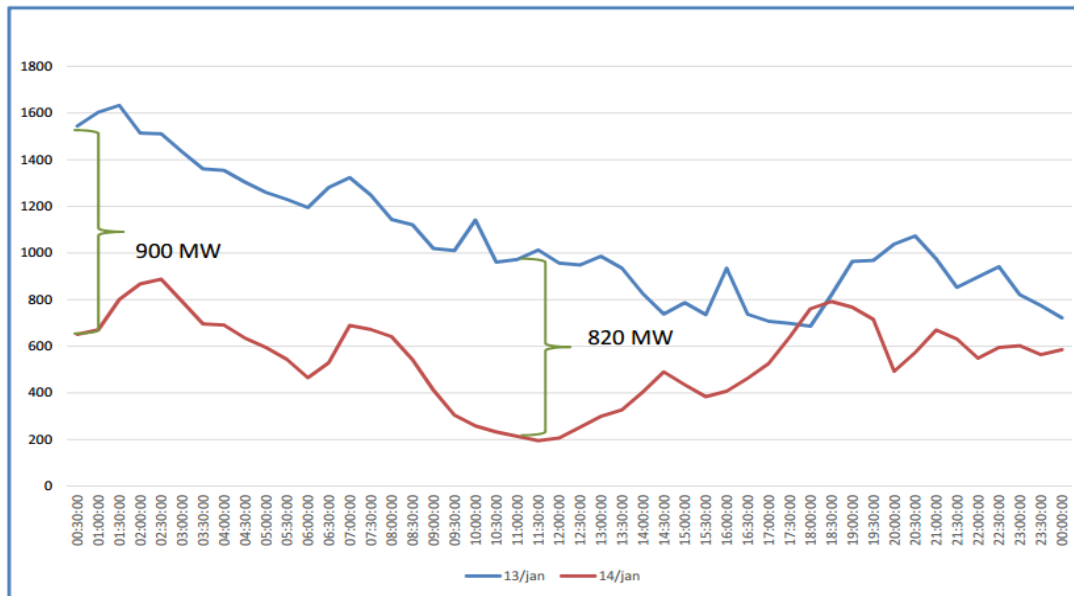
# Introduction

- ▶ Renewable sources such as wind and solar bring small time frame generation uncertainties



# Introduction

- ▶ Renewable sources such as wind and solar bring small time frame generation uncertainties



- ▶ We need hourly resolution !

# Introduction

- Number of variables in the optimization problem for Brazil system (1 month)

Constraints	3 Block problem	Hourly problem
Water balance constraints	161	+ 117,000
Load balance constraints	12	+ 2,900
Maximum generation & turbinning constraints	900	+219,000
Maximum & minimum volume constraints	322	+235,000
Total	1461	+573,000



# Introduction

- Number of variables in the optimization problem for Brazil system (1 month)

Constraints	3 Block problem	Hourly problem
Water balance constraints	161	+ 117,000
Load balance constraints	12	+ 2,900
Maximum generation & turbinning constraints	900	+219,000
Maximum & minimum volume constraints	322	+235,000
Total	1461	+573,000

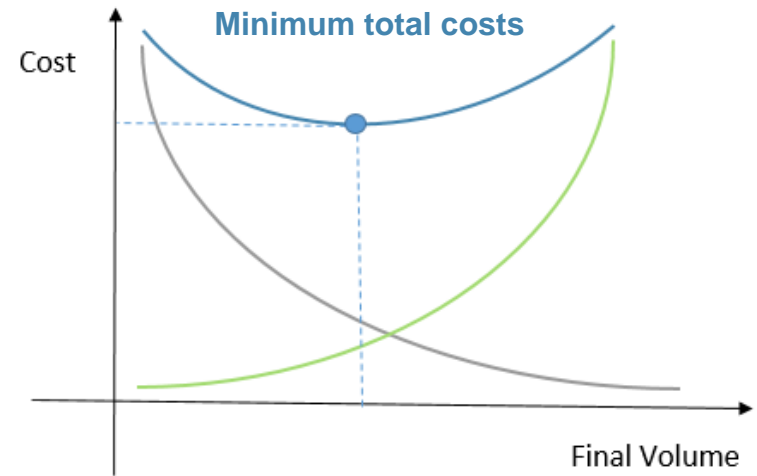
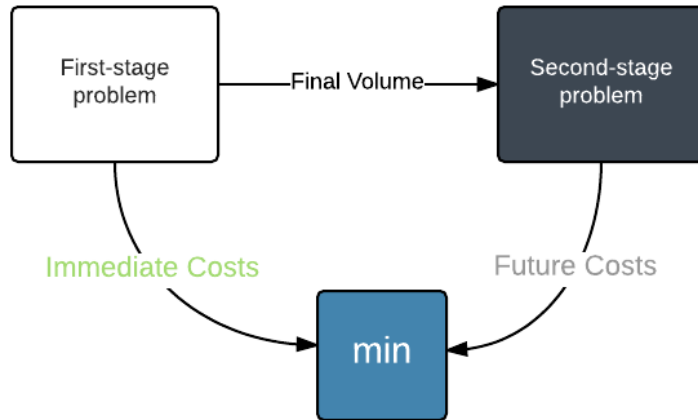
**How can we obtain hourly based results without representing hourly variables ?**

# Outline

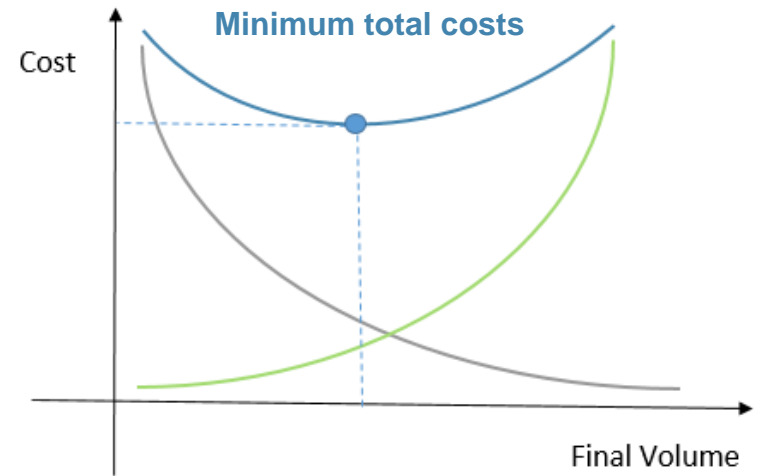
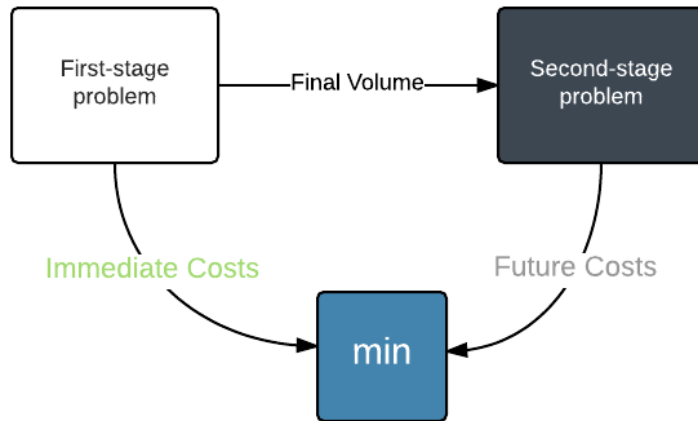
---

- ▶ Introduction
- ▶ **SDDP**
- ▶ Basic concepts
- ▶ Immediate cost function calculation method
- ▶ Results
- ▶ Final conclusions

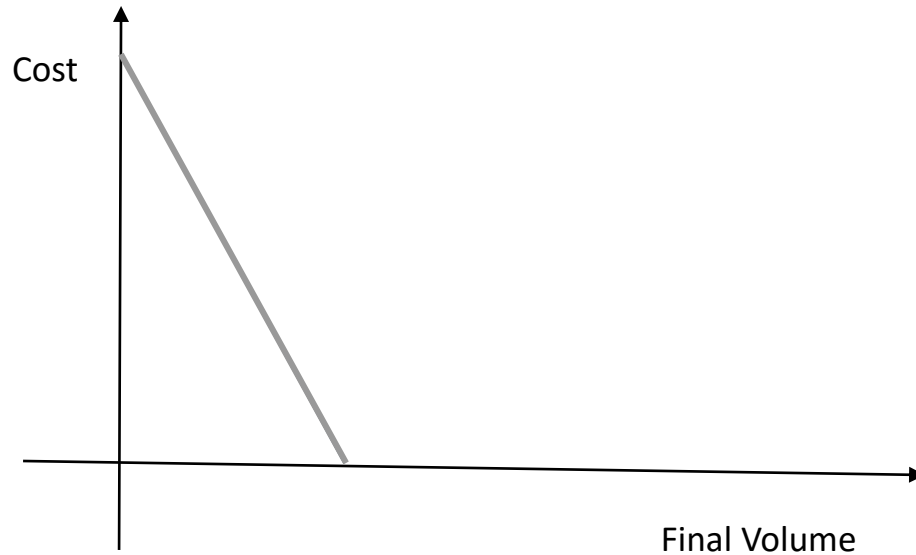
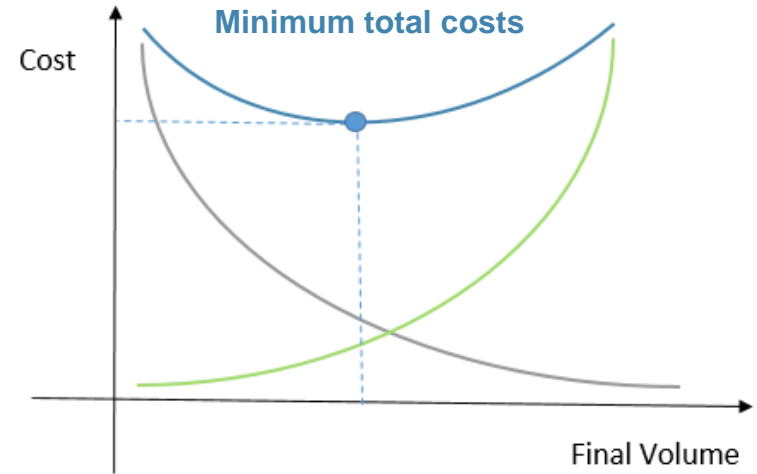
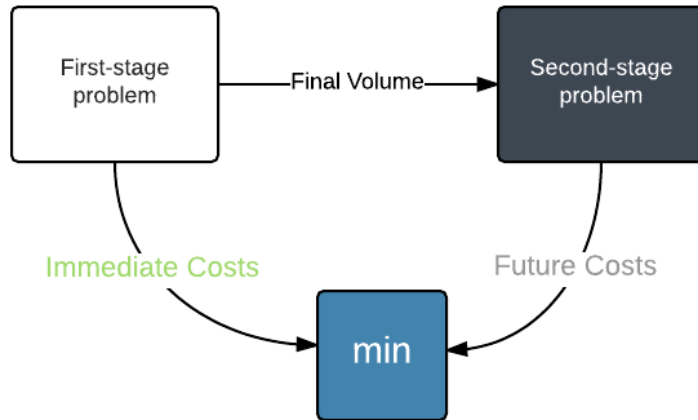
# SDDP



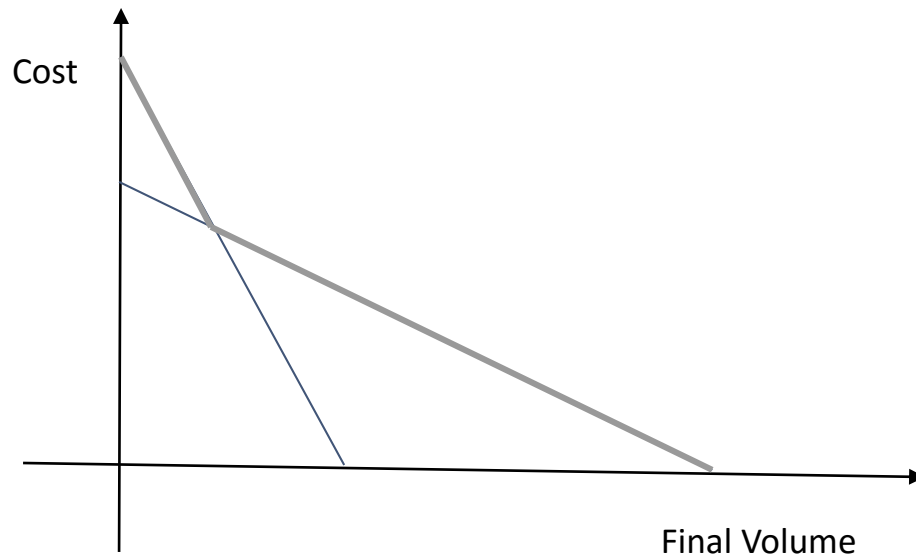
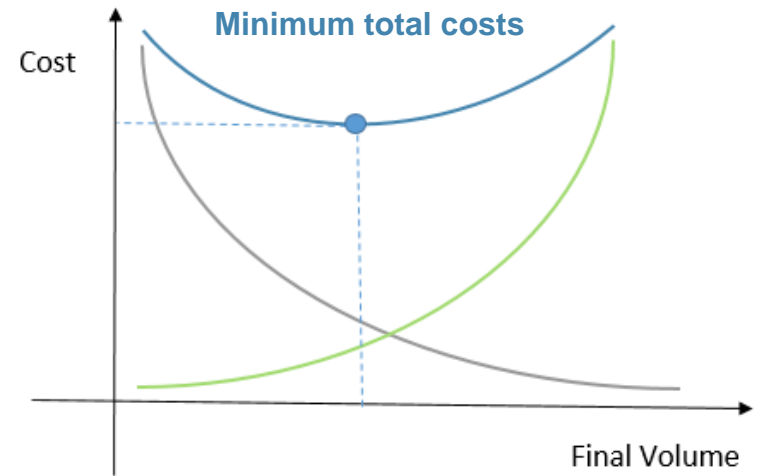
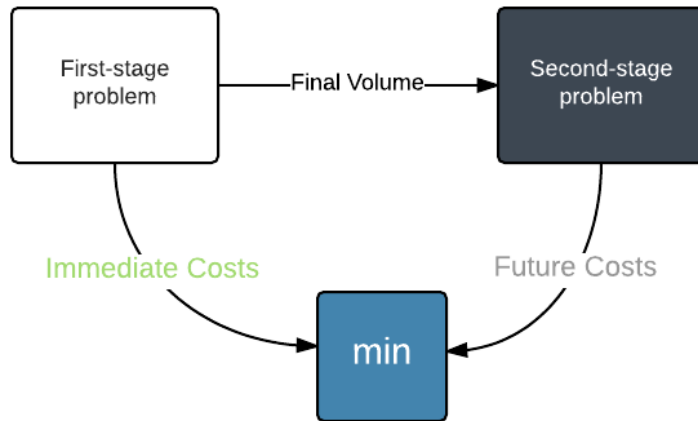
# SDDP



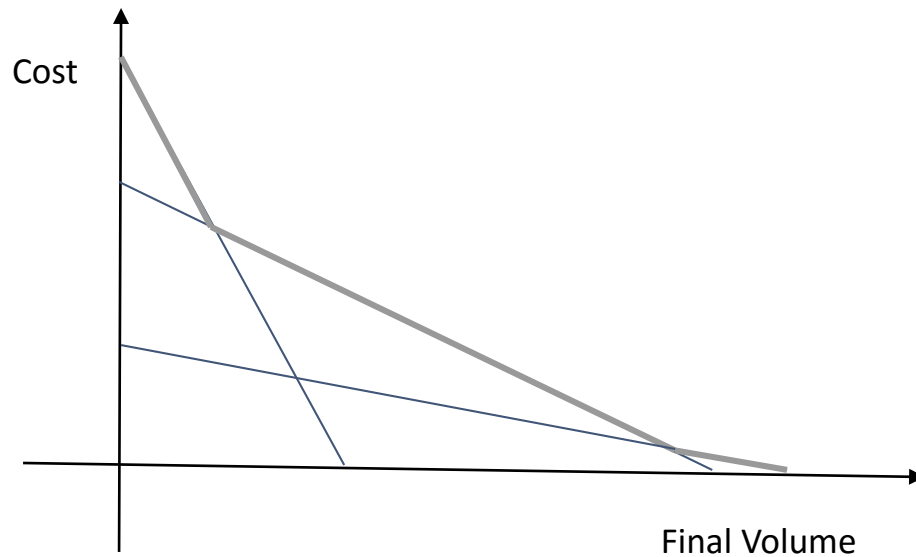
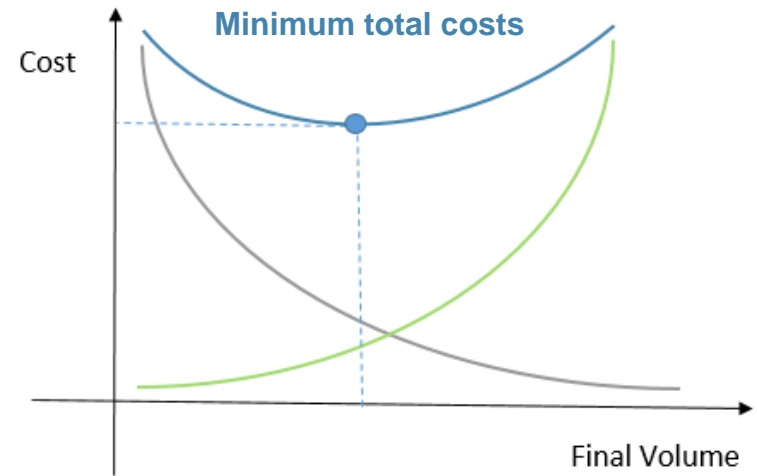
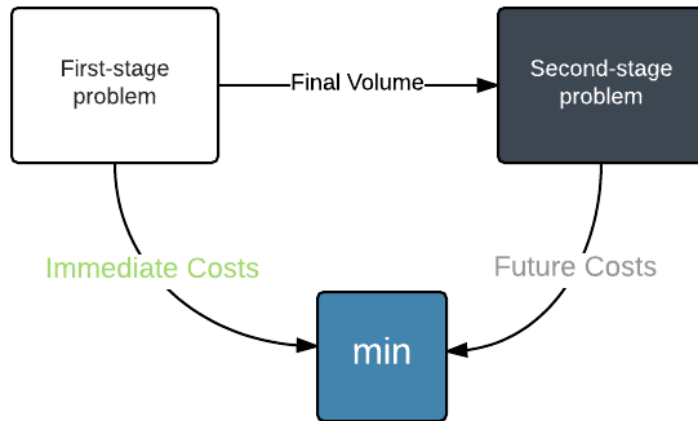
# SDDP



# SDDP



# SDDP



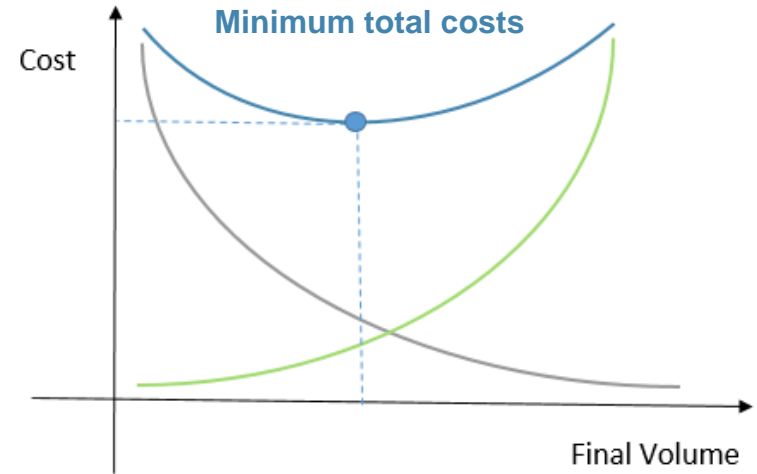
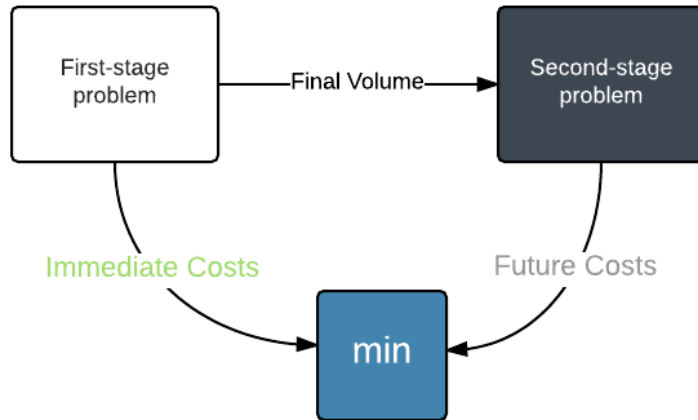
# Outline

---

- ▶ Introduction
- ▶ SDDP
- ▶ Basic concepts
- ▶ Immediate cost function calculation method
- ▶ Results
- ▶ Final conclusions

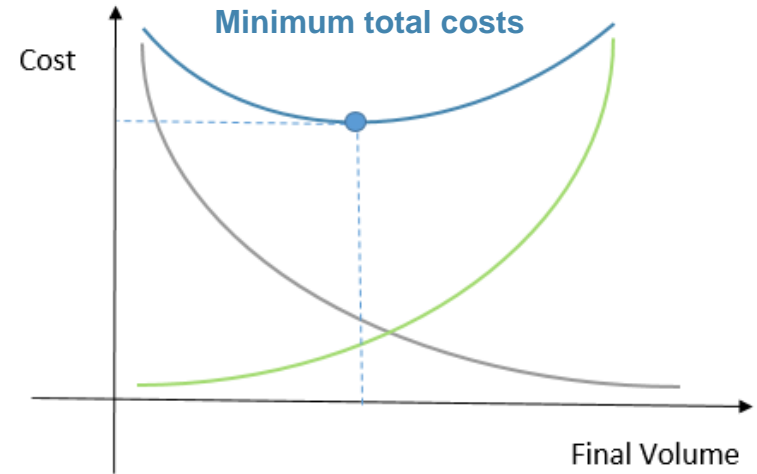
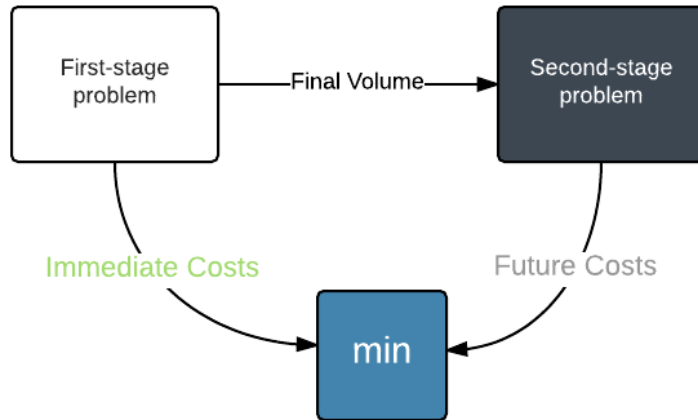


# Basic concepts



$$\begin{array}{ll}
 \min & \sum cg \\
 & v_{t+1} = v_t + a - u - s \\
 & \rho u + g = d \\
 & \rho u = e \\
 & u \leq \bar{u} \\
 & g \leq \bar{g} \\
 & + \alpha \\
 & \alpha \geq bv_{t+1} + c
 \end{array}$$

# Basic concepts



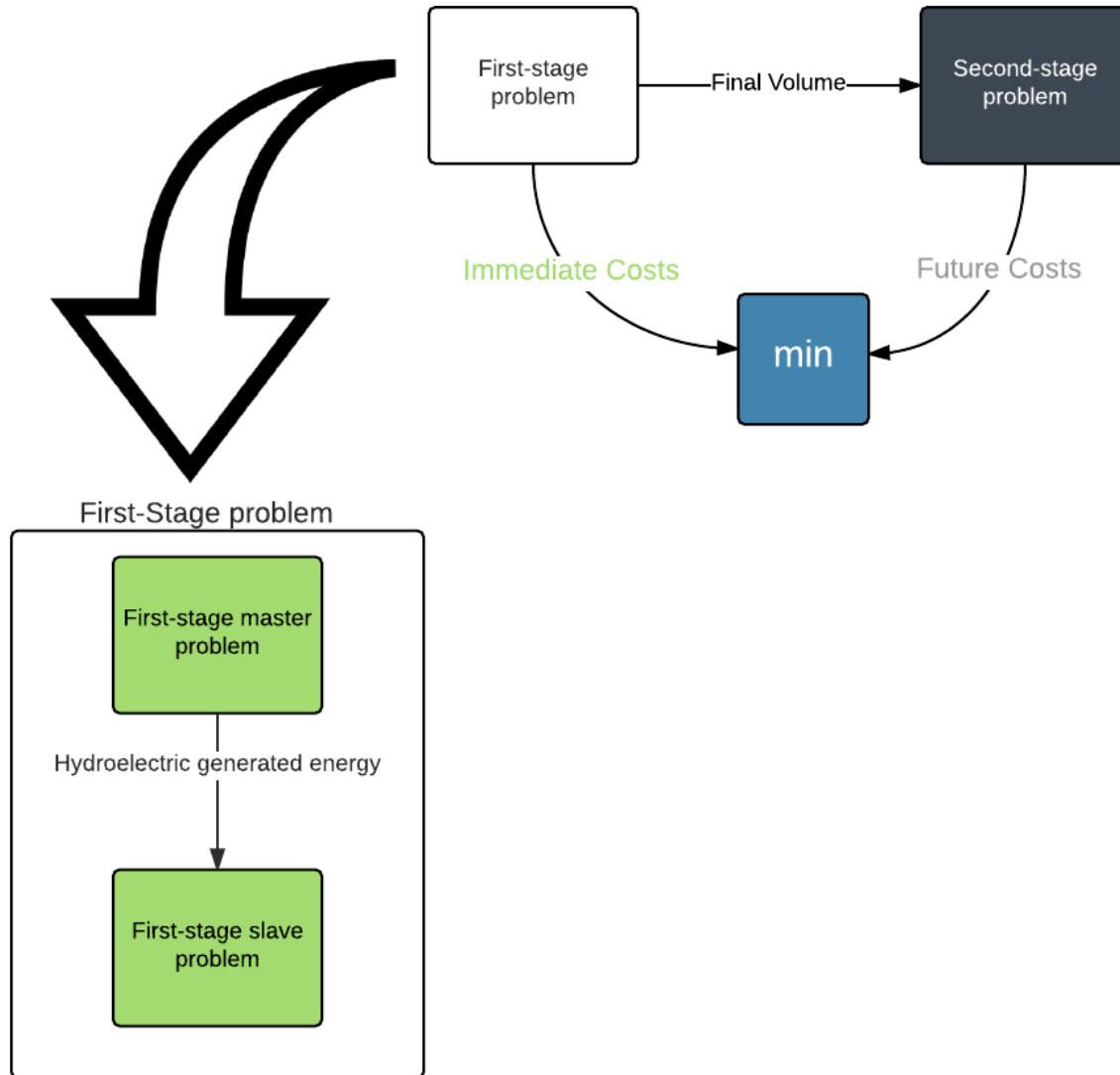
$$\begin{array}{ll}
 \min & \sum cg \\
 & v_{t+1} = v_t + a - u - s \\
 & \rho u + g = d \\
 & \rho u = e \\
 & u \leq \bar{u} \\
 & g = g \\
 & + \alpha \\
 & \alpha \geq bv_{t+1} + c
 \end{array}$$

No thermal constraints and no hourly variables

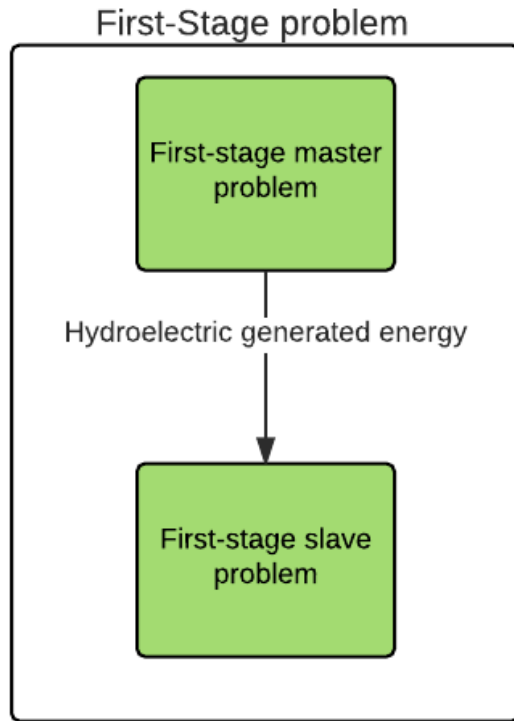


$$\begin{array}{ll}
 \min & \beta \\
 & v_{t+1} = v_t + a - u - s \\
 & \rho u - e = 0 \\
 & \beta \geq be + c \\
 & + \alpha \\
 & \alpha \geq bv_{t+1} + c
 \end{array}$$

# Basic concepts



# Basic concepts



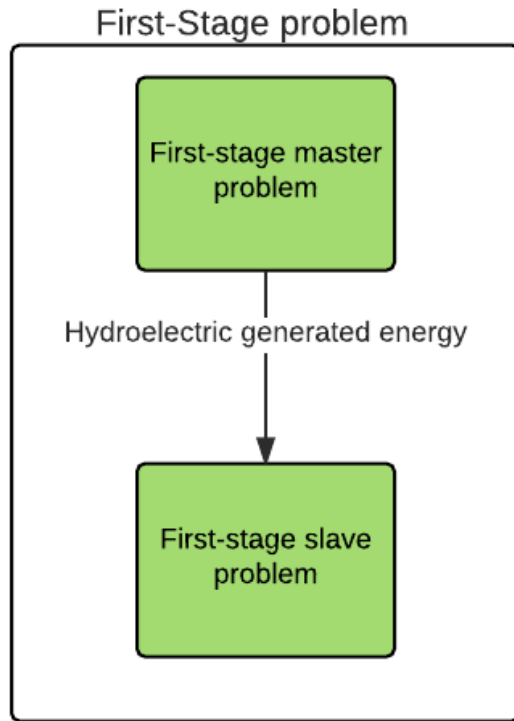
$$\begin{array}{ll}
 \min & \beta \quad + \quad \alpha \\
 & v_{t+1} = v_t + a - u - s \\
 & \rho u - e = 0 \\
 & \beta \geq be + c \\
 & \alpha \geq bv_{t+1} + c
 \end{array}$$



$e^*$

$$\begin{array}{l}
 \min \sum_{\tau} \sum_j c_j g_{\tau,j} \\
 \sum_{\tau} e_{\tau} = e^* \\
 e_{\tau} + \sum_j g_{\tau,j} = d_{\tau}, \forall \tau \\
 e_{\tau} \leq \bar{e}, \forall \tau \\
 g_{\tau,j} \leq \bar{g}, \forall \tau, j
 \end{array}$$

# Basic concepts

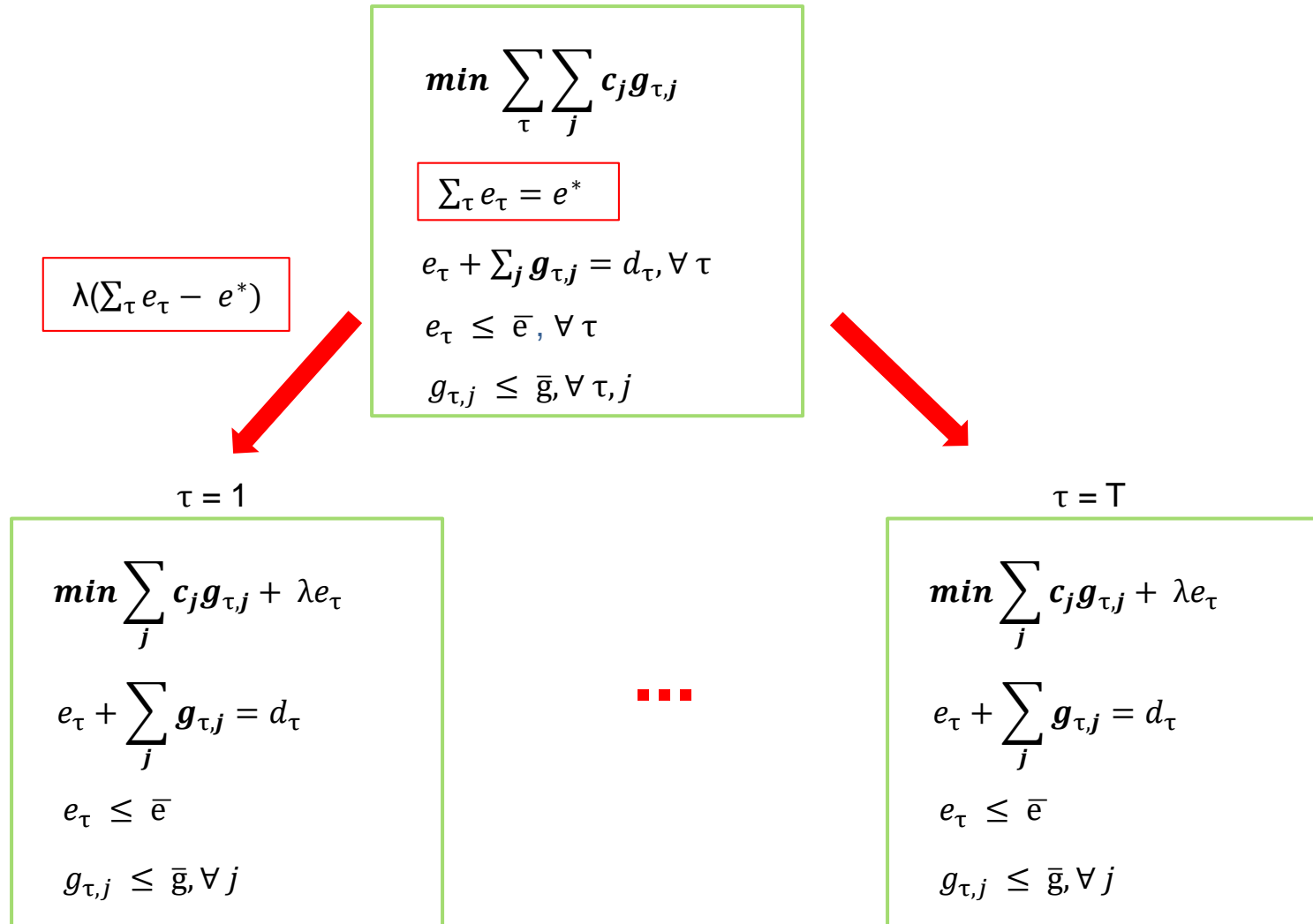


$$\begin{array}{ll}
 \min & \beta \quad + \quad \alpha \\
 & v_{t+1} = v_t + a - u - s \\
 & \rho u - e = 0 \\
 & \beta \geq be + c \\
 & \alpha \geq bv_{t+1} + c
 \end{array}$$

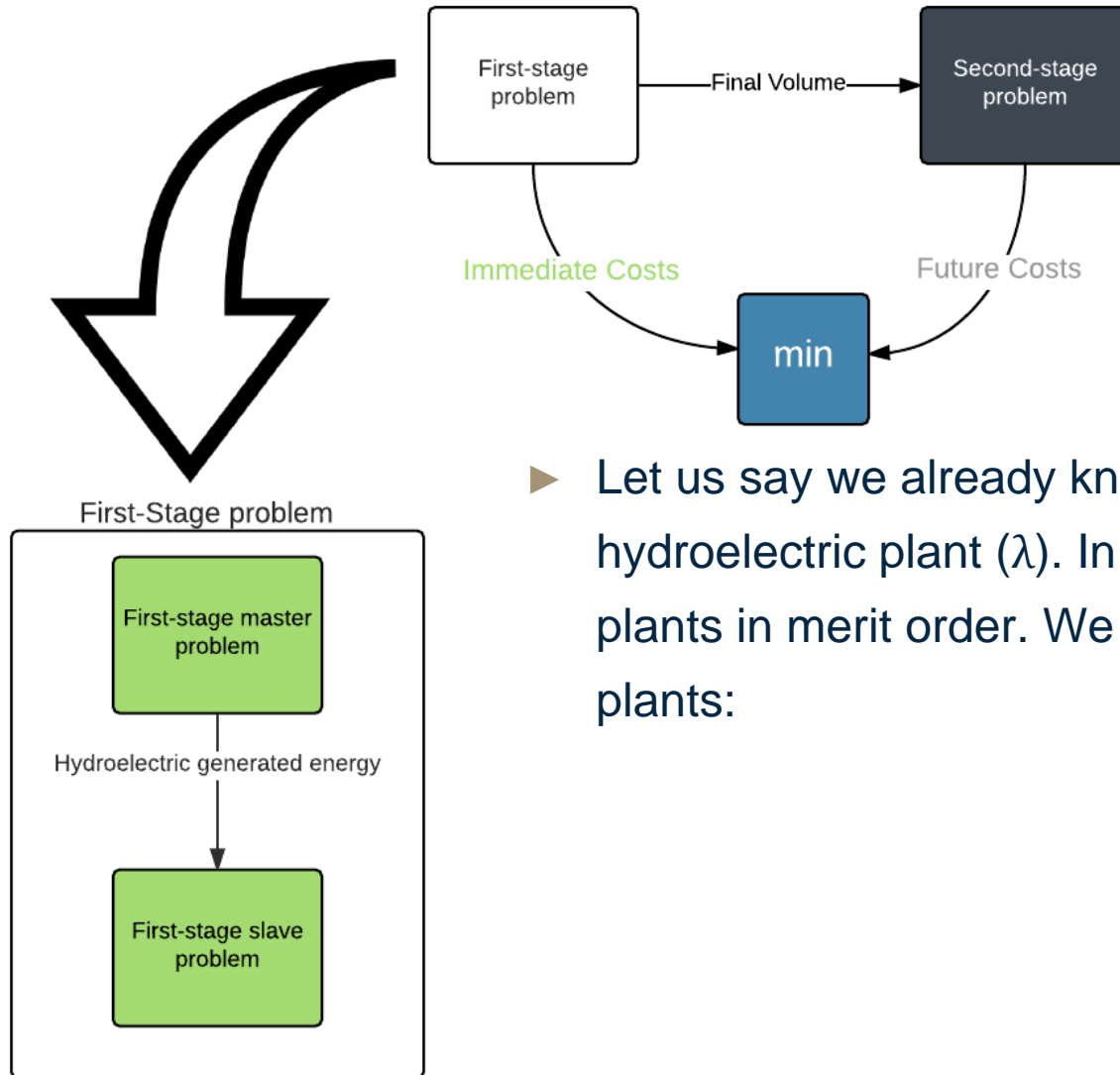


$$\begin{array}{l}
 \min \sum_{\tau} \sum_j c_j g_{\tau,j} \\
 \boxed{\sum_{\tau} e_{\tau} = e^*} \\
 e_{\tau} + \sum_j g_{\tau,j} = d_{\tau}, \forall \tau \\
 e_{\tau} \leq \bar{e}, \forall \tau \\
 g_{\tau,j} \leq \bar{g}, \forall \tau, j
 \end{array}$$

# Basic concepts

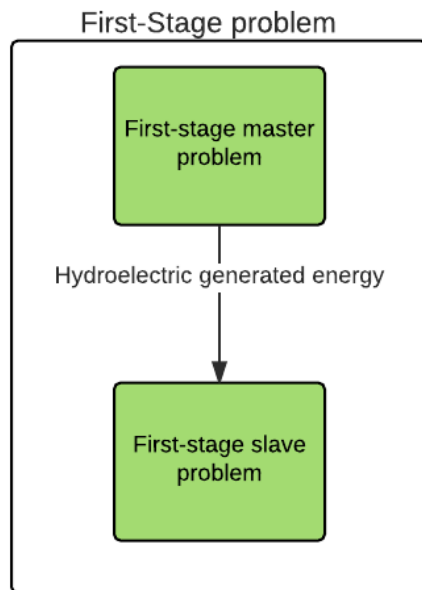
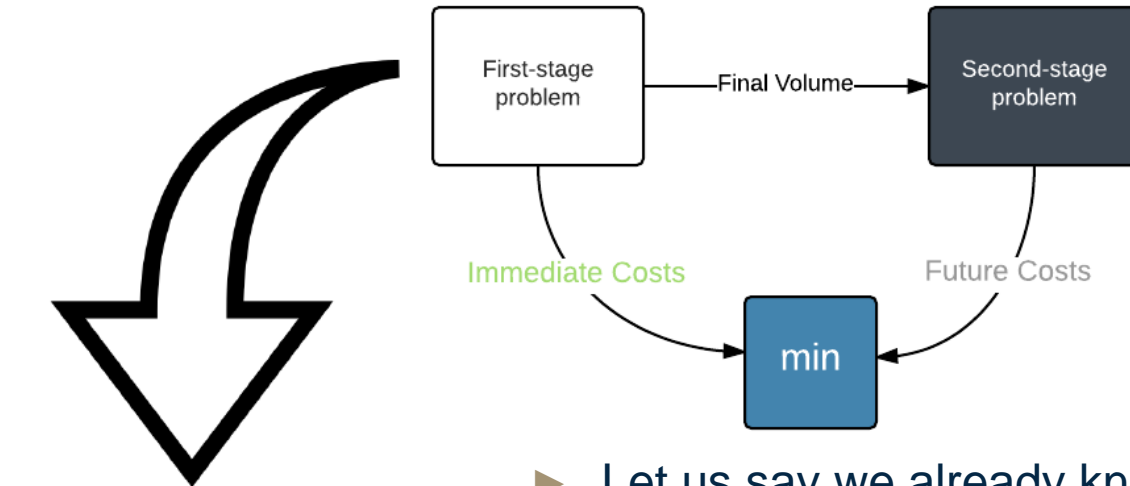


# Basic concepts

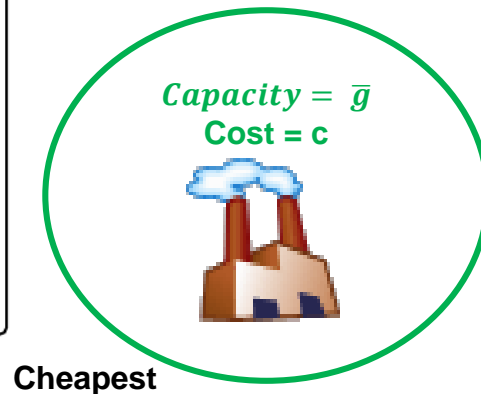


- Let us say we already know the opportunity cost of the hydroelectric plant ( $\lambda$ ). In this case, all know how to order plants in merit order. We have the following thermal plants:

# Basic concepts

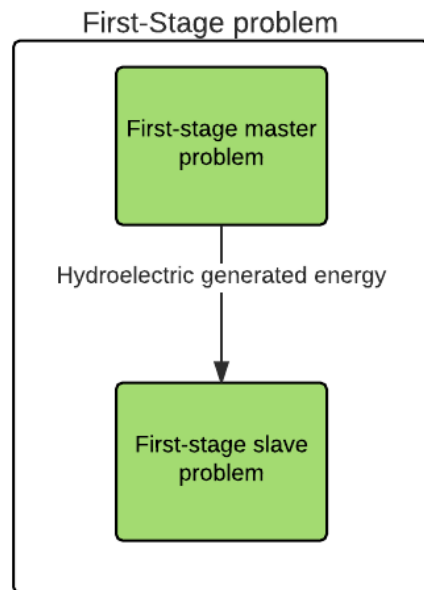
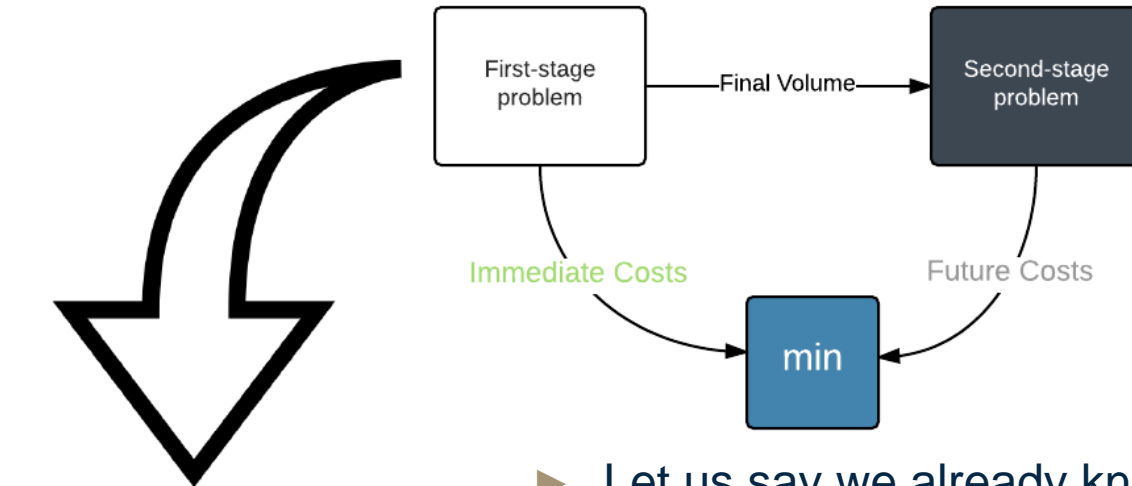


- Let us say we already know the opportunity cost of the hydroelectric plant ( $\lambda$ ). In this case, all know how to order plants in merit order. We have the following thermal plants:

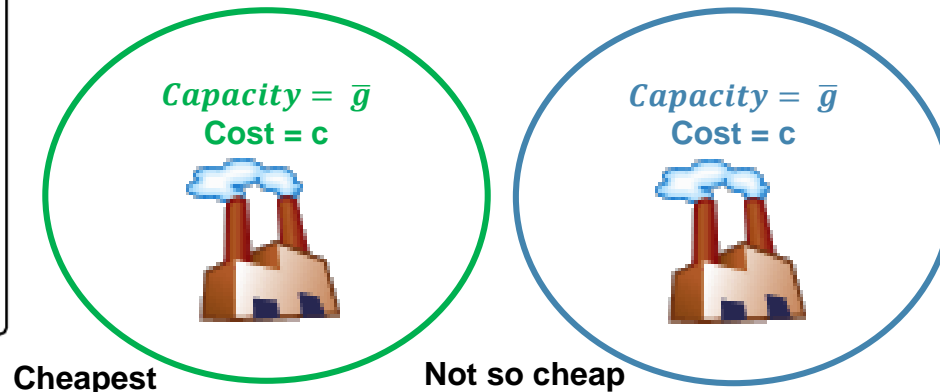




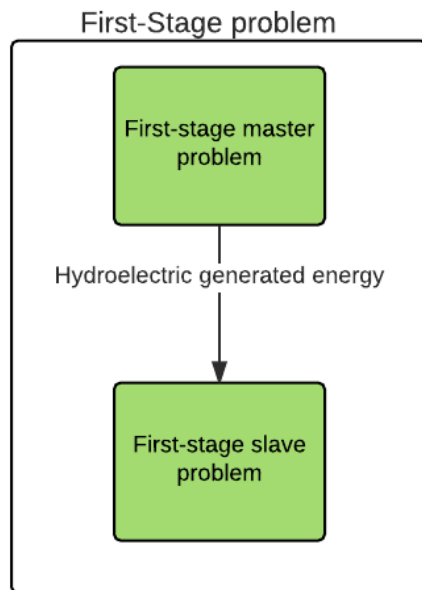
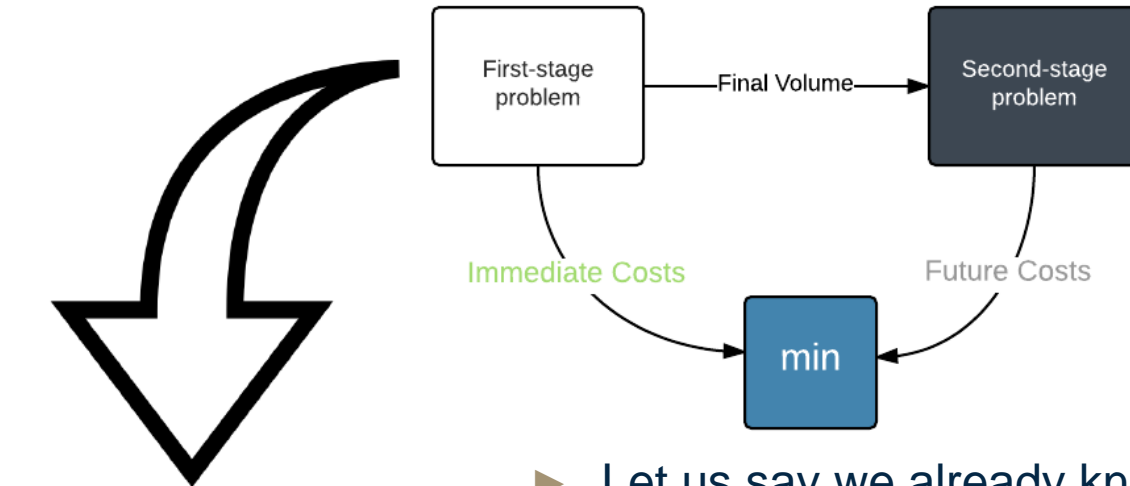
# Basic concepts



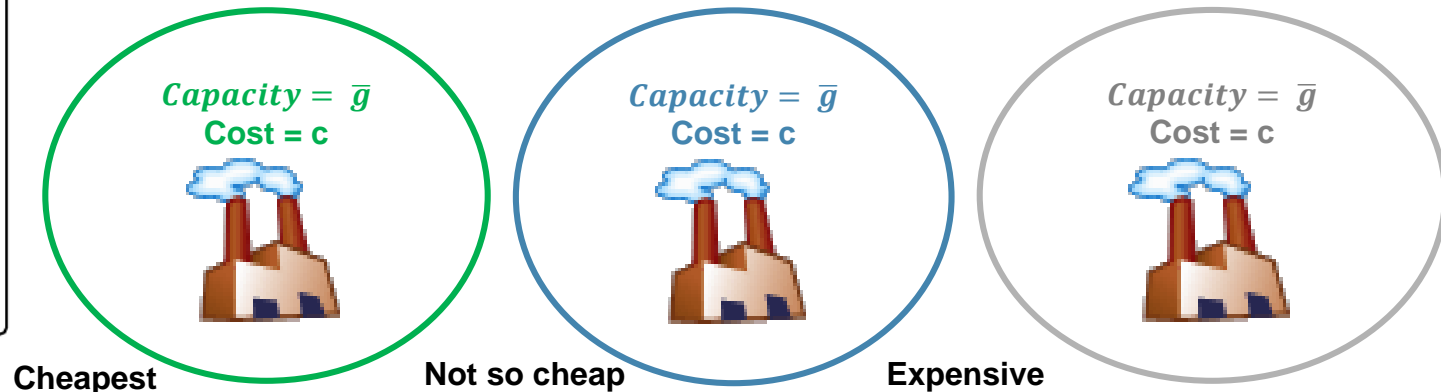
- Let us say we already know the opportunity cost of the hydroelectric plant ( $\lambda$ ). In this case, all know how to order plants in merit order. We have the following thermal plants:



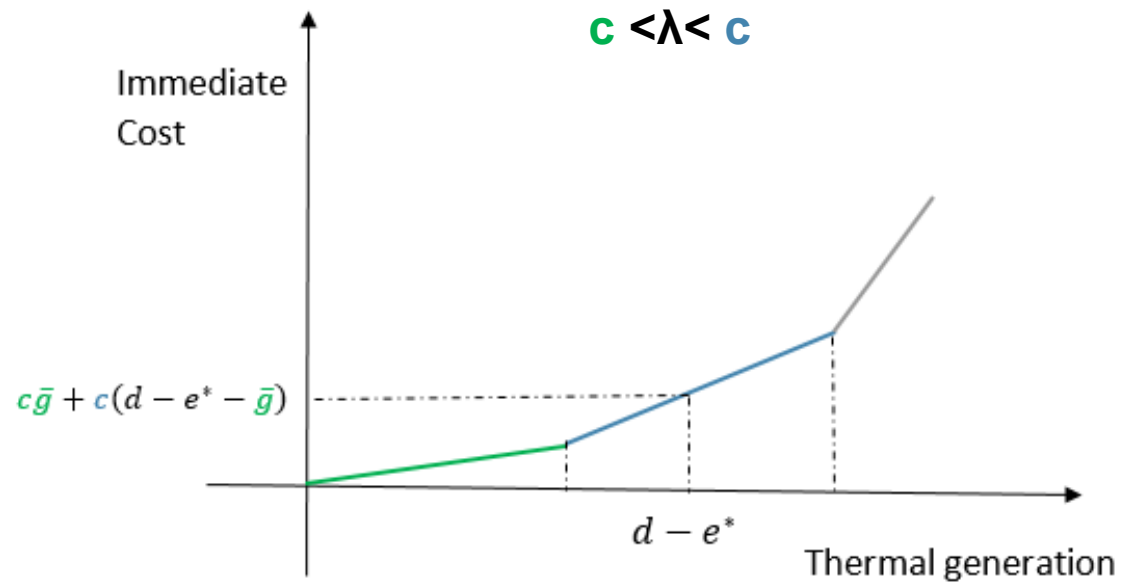
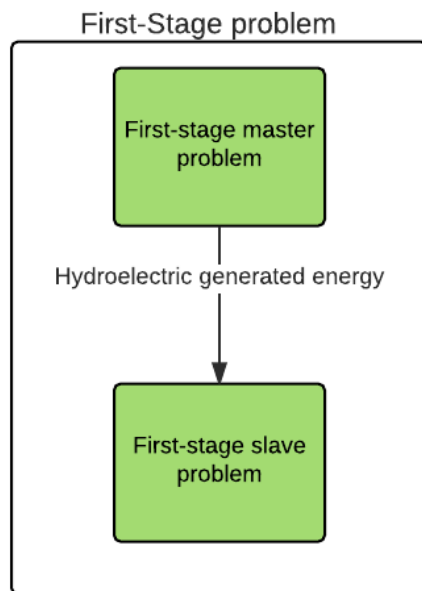
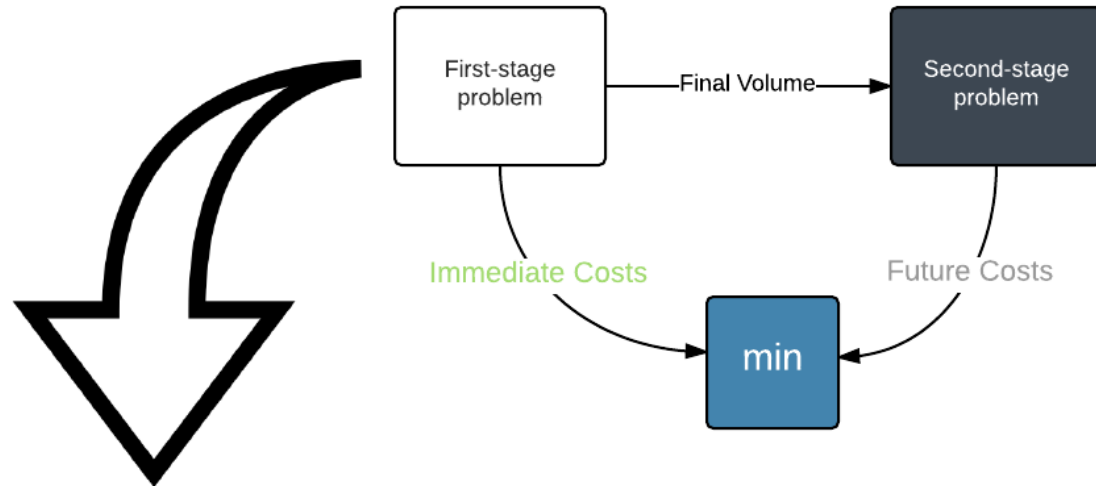
# Basic concepts



- Let us say we already know the opportunity cost of the hydroelectric plant ( $\lambda$ ). In this case, all know how to order plants in merit order. We have the following thermal plants:



# Basic concepts



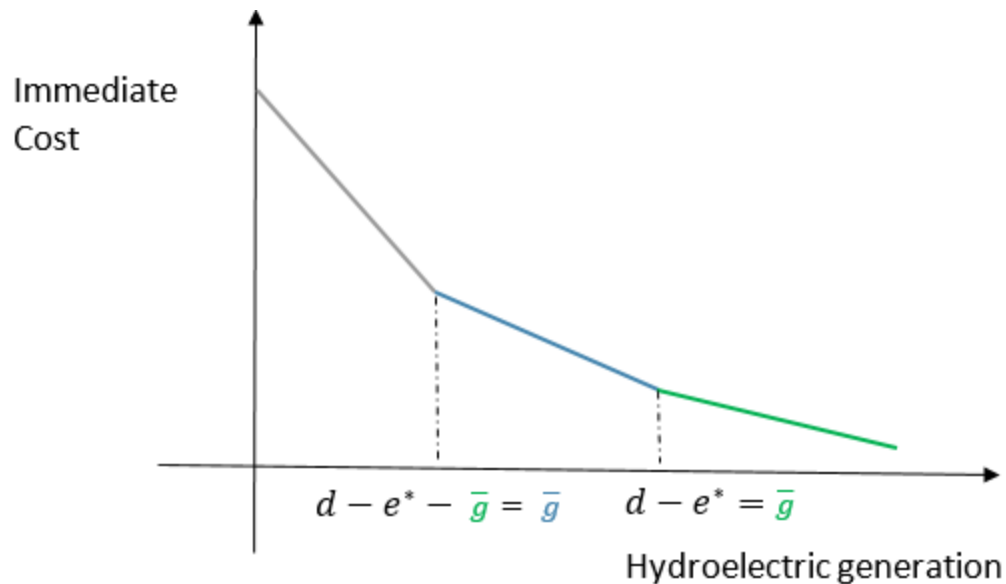
# Outline

---

- ▶ Introduction
- ▶ SDDP
- ▶ Basic concepts
- ▶ Immediate cost function calculation method
- ▶ Results
- ▶ Final conclusions

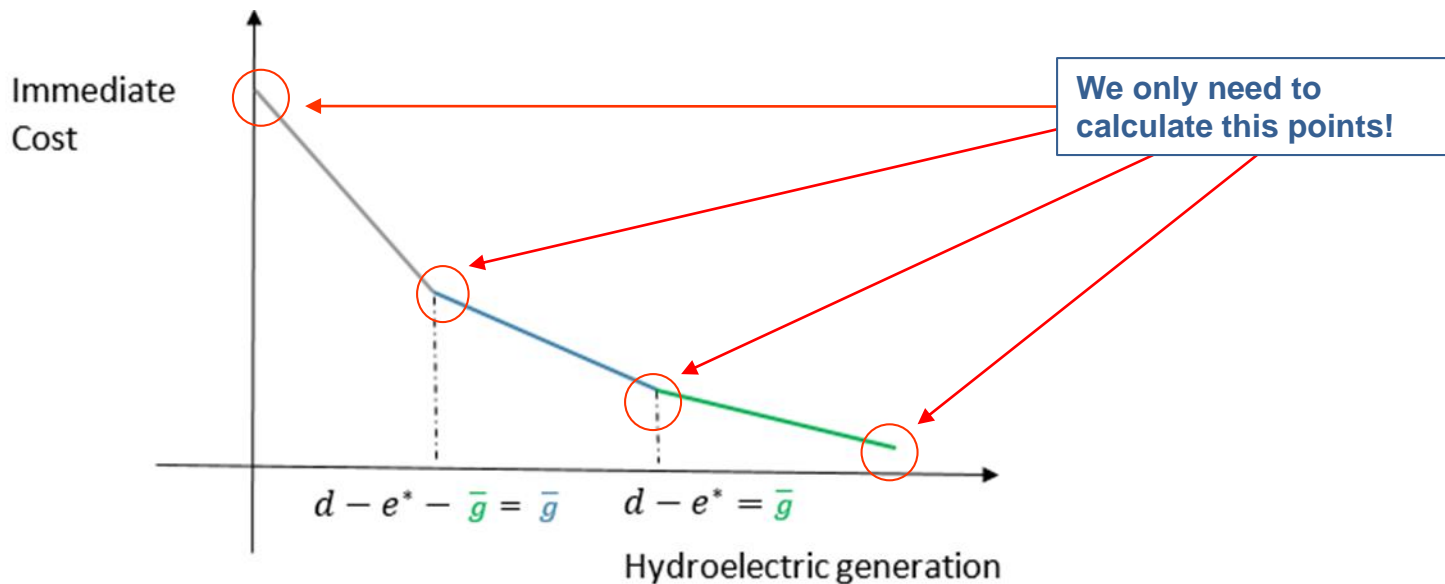
# Immediate cost function calculation method

- How can we calculate the immediate cost function?
  - If we calculate the immediate cost for several possible hydroelectric generations scenarios:



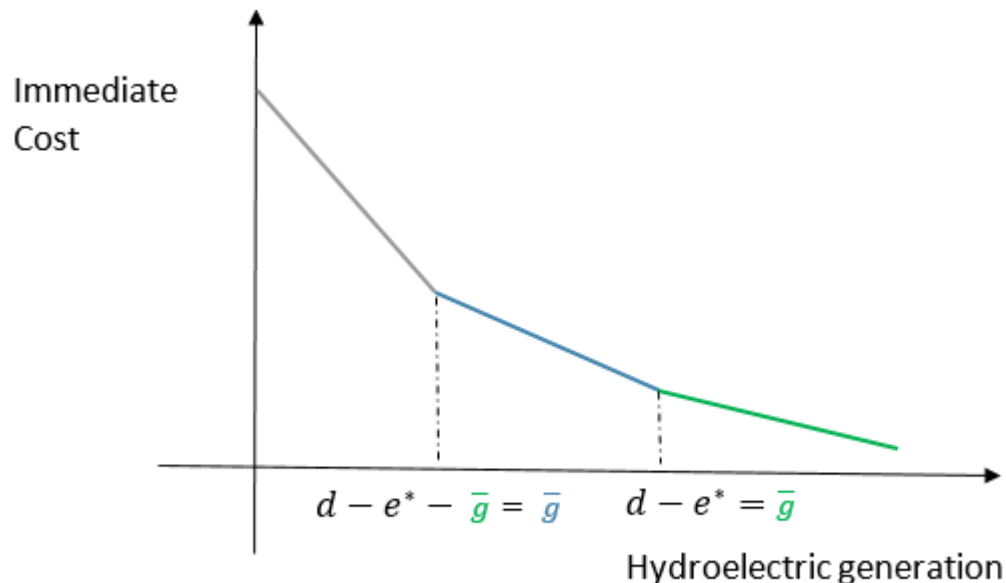
# Immediate cost function calculation method

- How can we calculate the immediate cost function?
  - If we calculate the immediate cost for several possible hydroelectric generations scenarios:



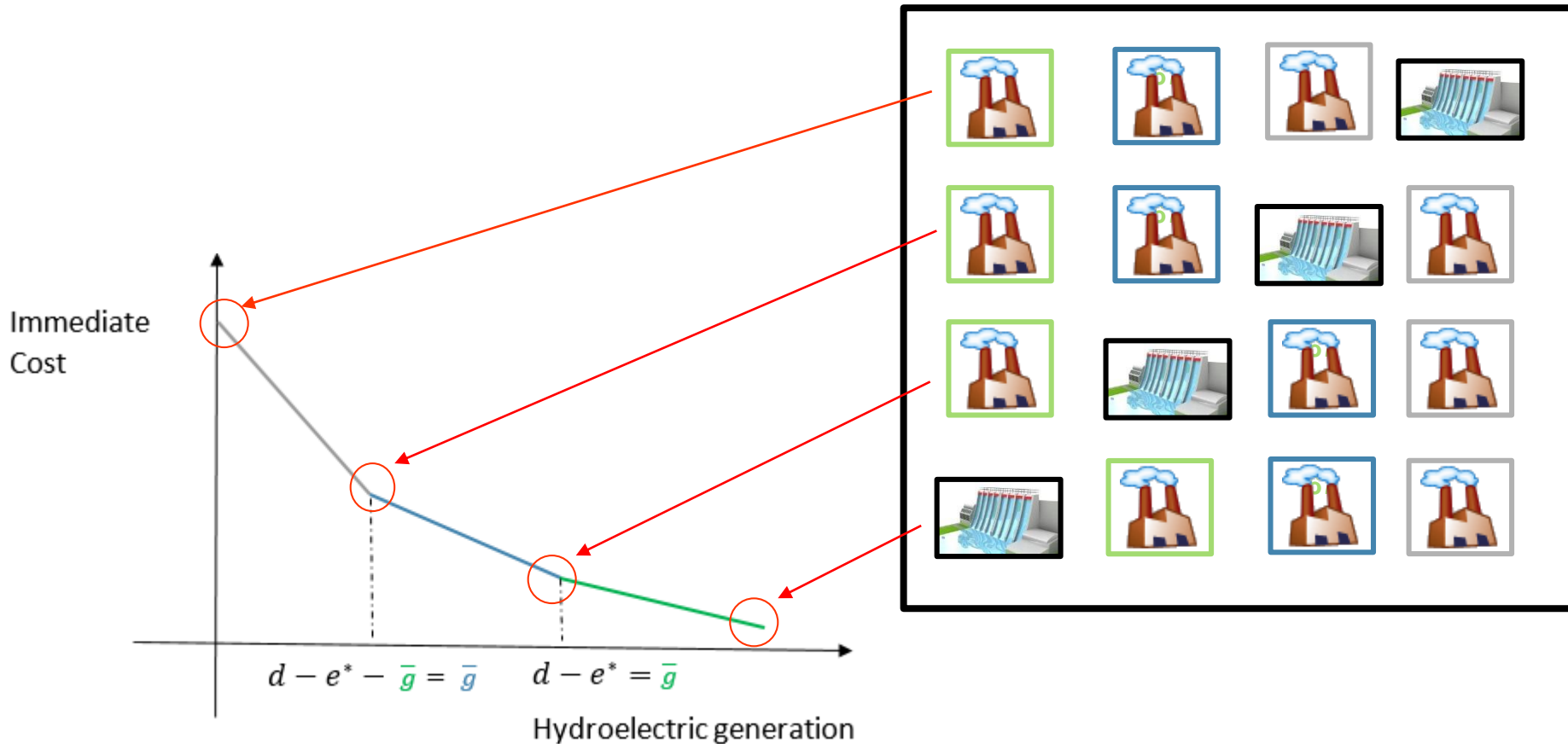
# Immediate cost function calculation method

- We can calculate the immediate cost function by enumerating all possible hydroelectric positions:



# Immediate cost function calculation method

- We can calculate the immediate cost function by enumerating all possible hydroelectric positions:





# Immediate cost function calculation method

- ▶ Intersection points are related to hydro plant dispatch position
- ▶ For every hour of a given stage (month or week) and hydroelectric position, we can calculate the optimal immediate cost:

- First, we need to calculate the optimal generation for every thermal plant  $i$ :

$$g_i = \bar{g}_i \times \min \left\{ 1, \frac{\delta^\tau}{\bar{g}_i} \right\}$$

- Where  $\delta^\tau$  is the residual demand considering all generators before  $i$  in dispatch order
- The immediate cost is obtained by calculating  $\sum_i c_i g_i$

# Immediate cost function calculation method

- Furthermore, we can discover mid dispatches only by having dispatches with the hydro plant in first and last positions.

Method	Number of operations
Optimization – discretization of function in equal intervals	100
Calculation of points for every hydro plant position	4
Calculation of points for hydro plant in first and last positions	2

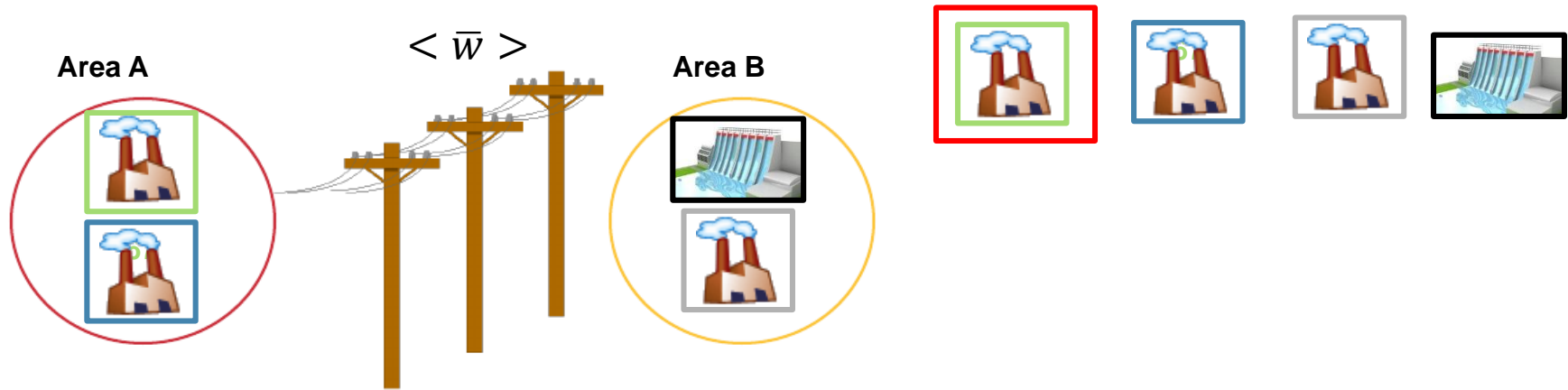
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



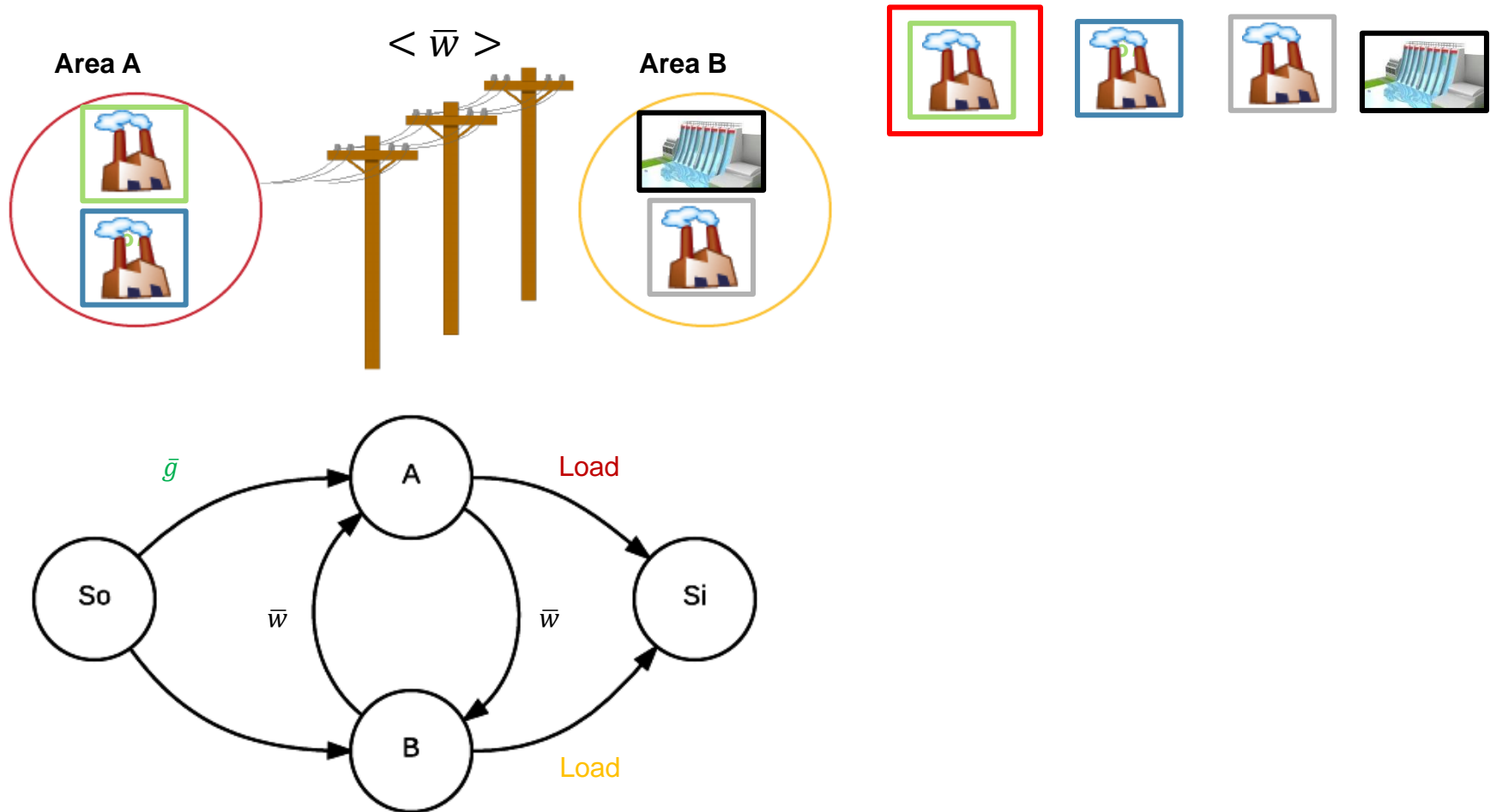
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



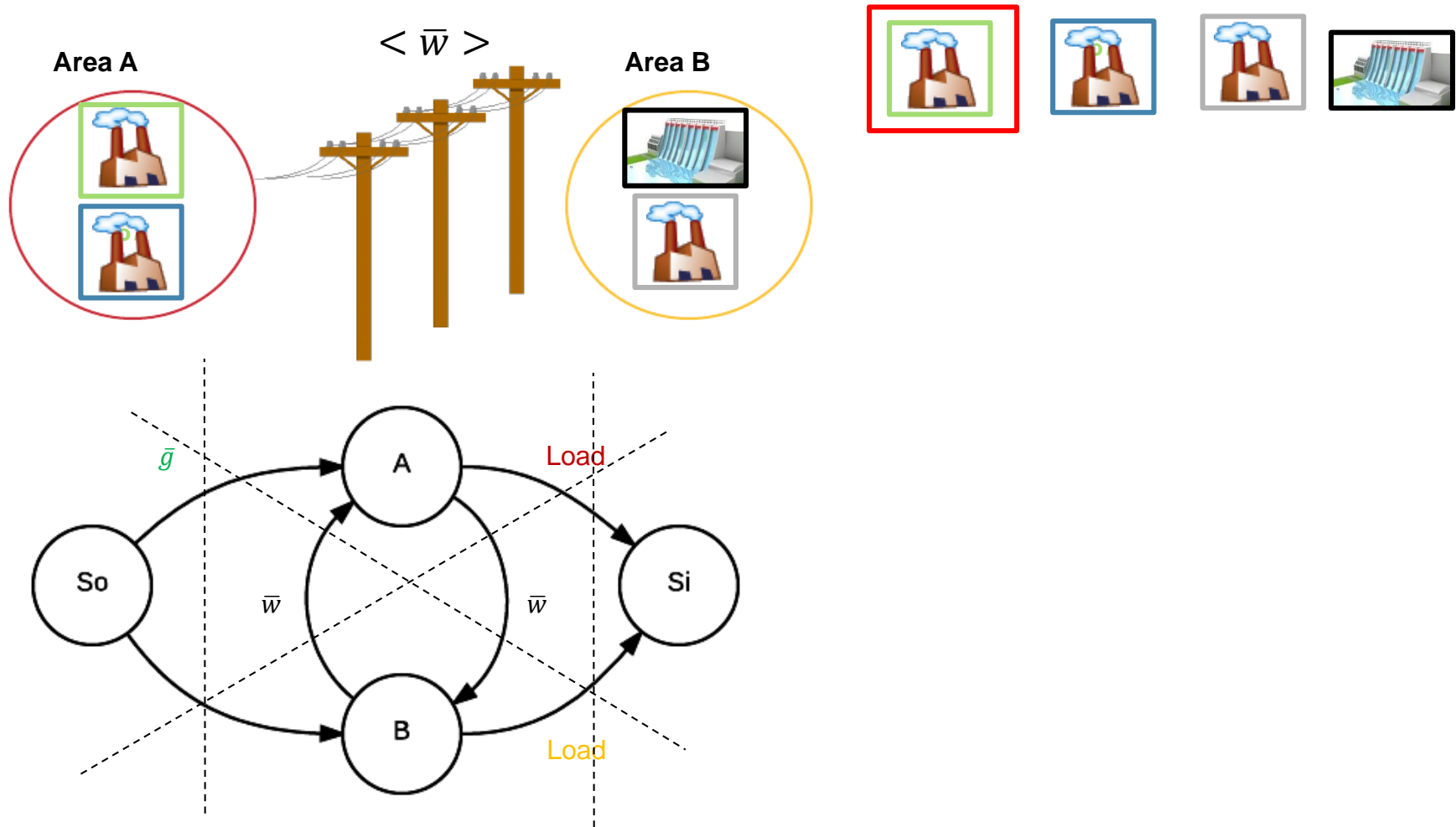
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



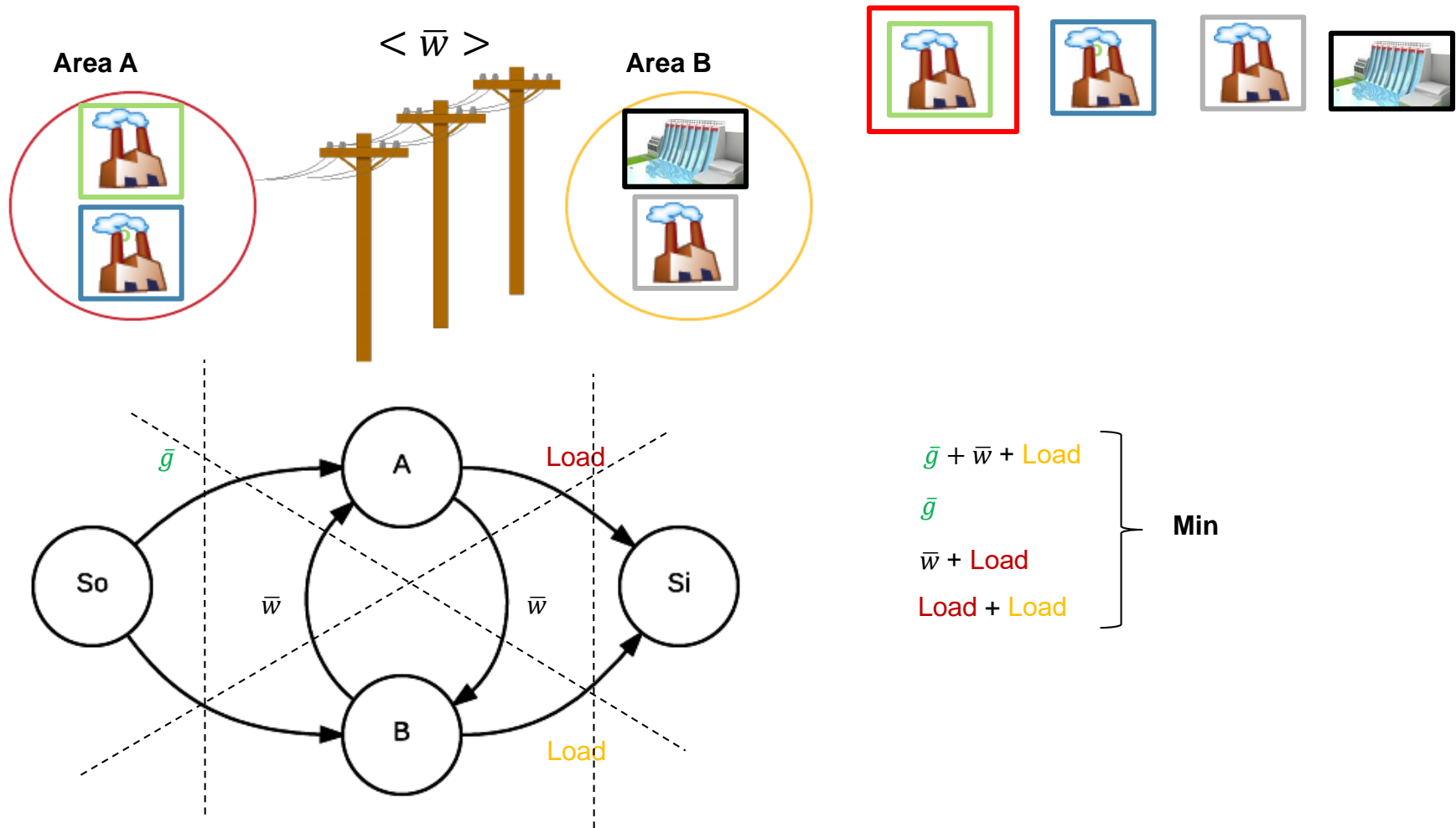
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



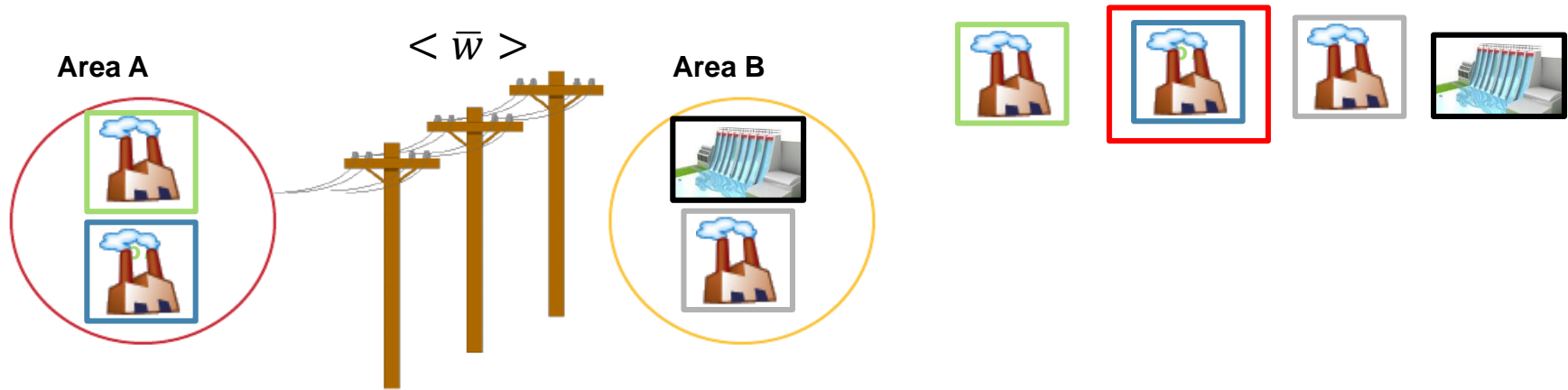
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



# Immediate cost function calculation method

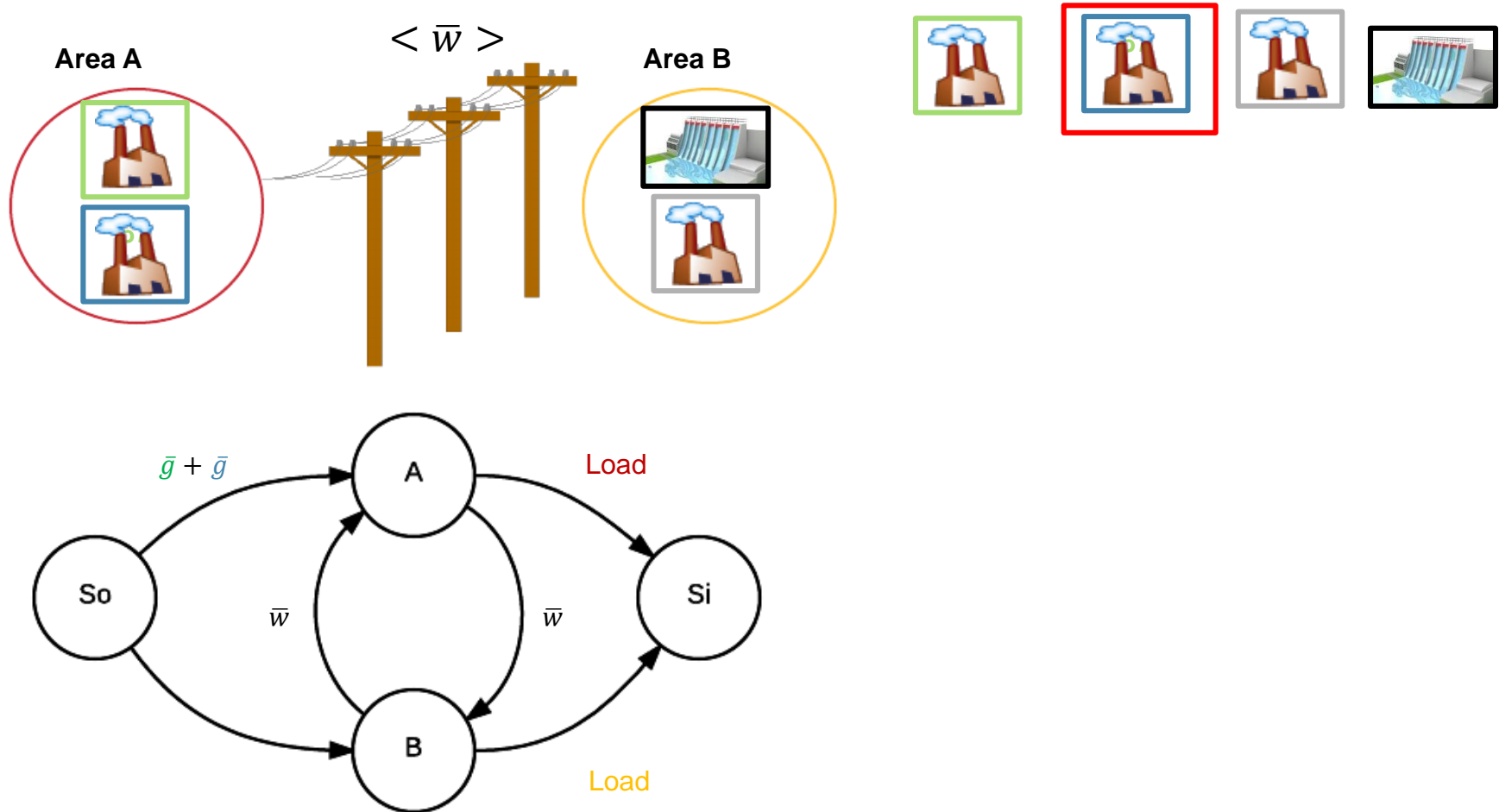
- In multi-area systems, we need to use min cut approach:





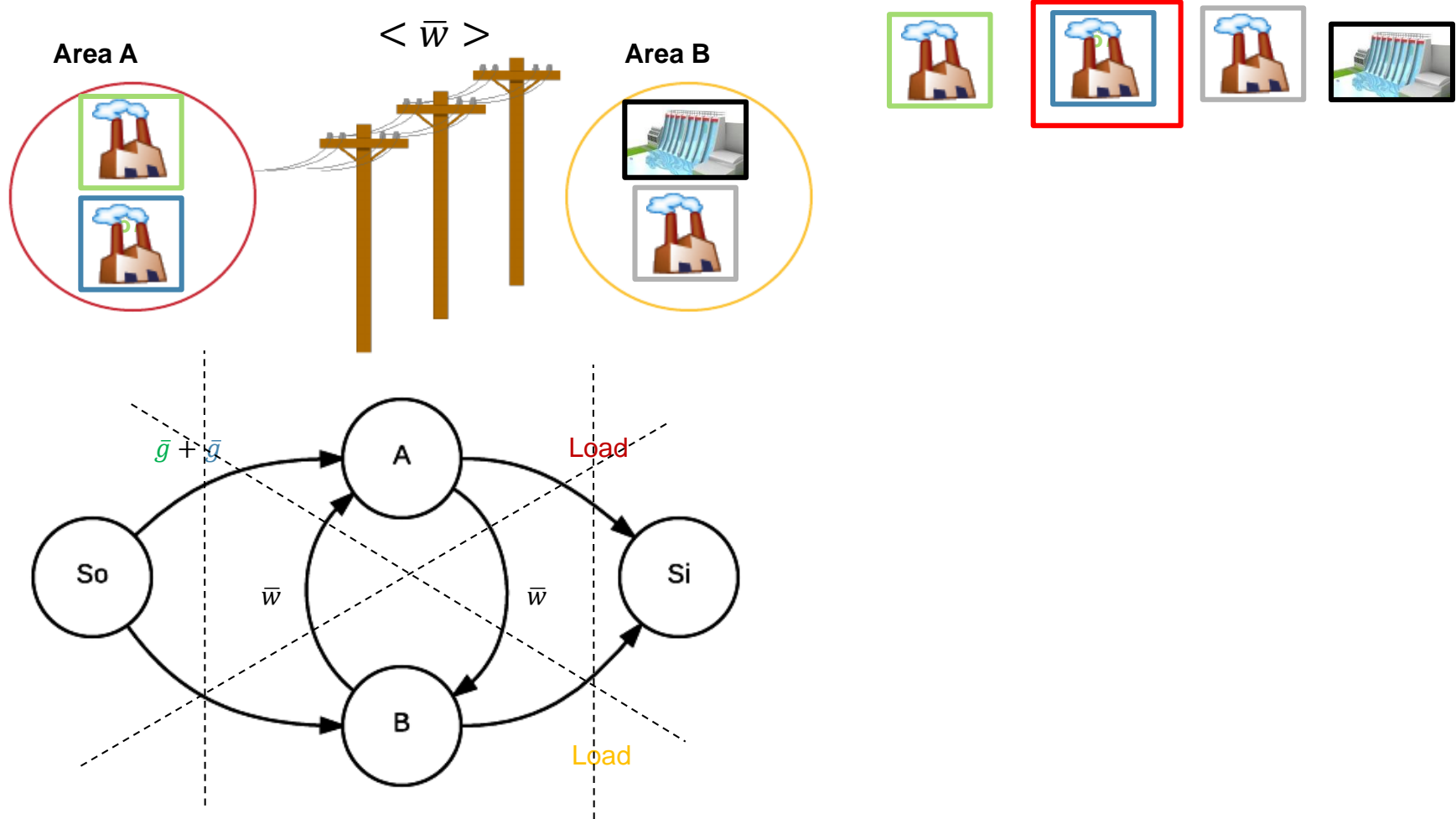
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



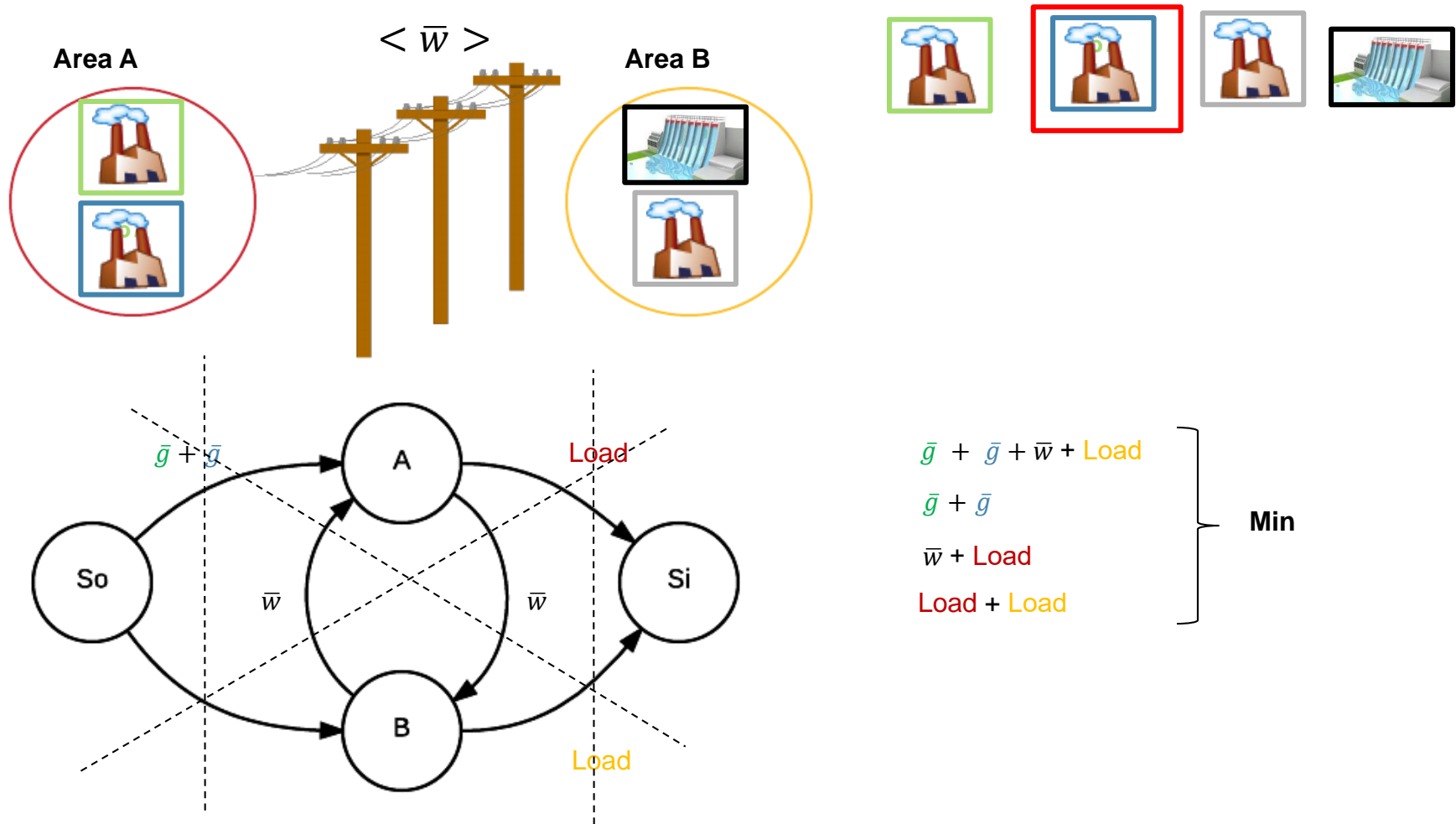
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



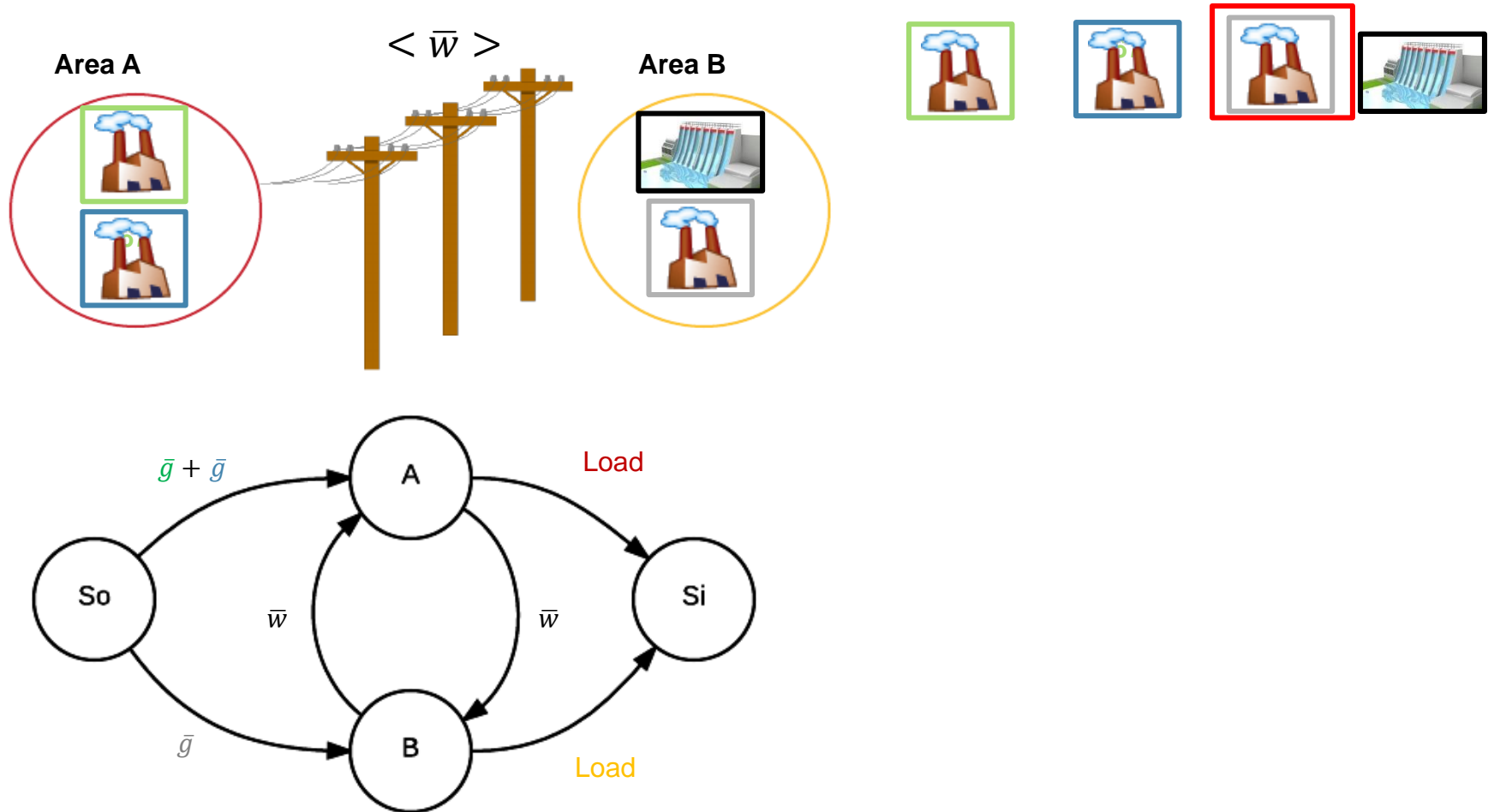
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



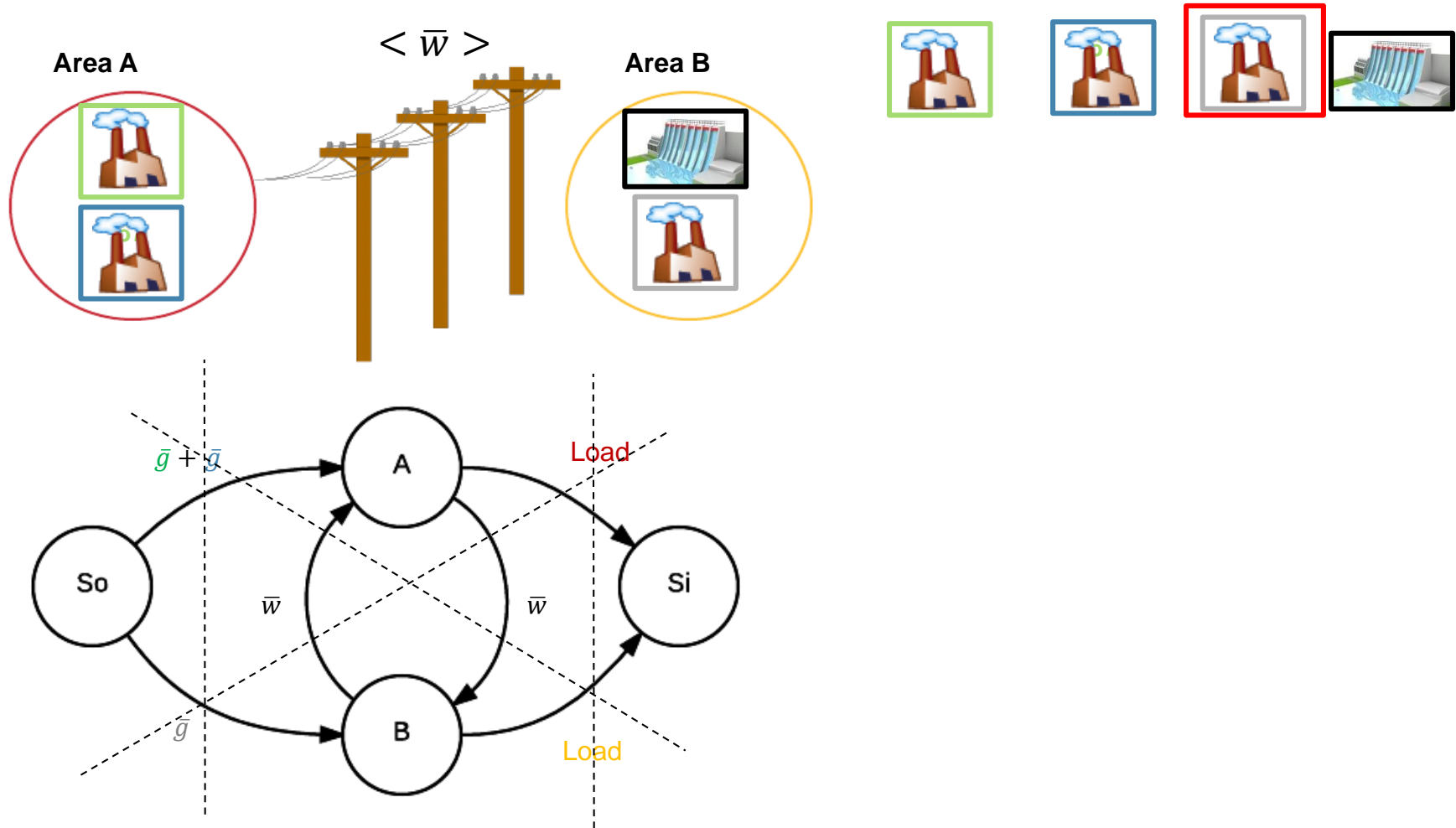
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



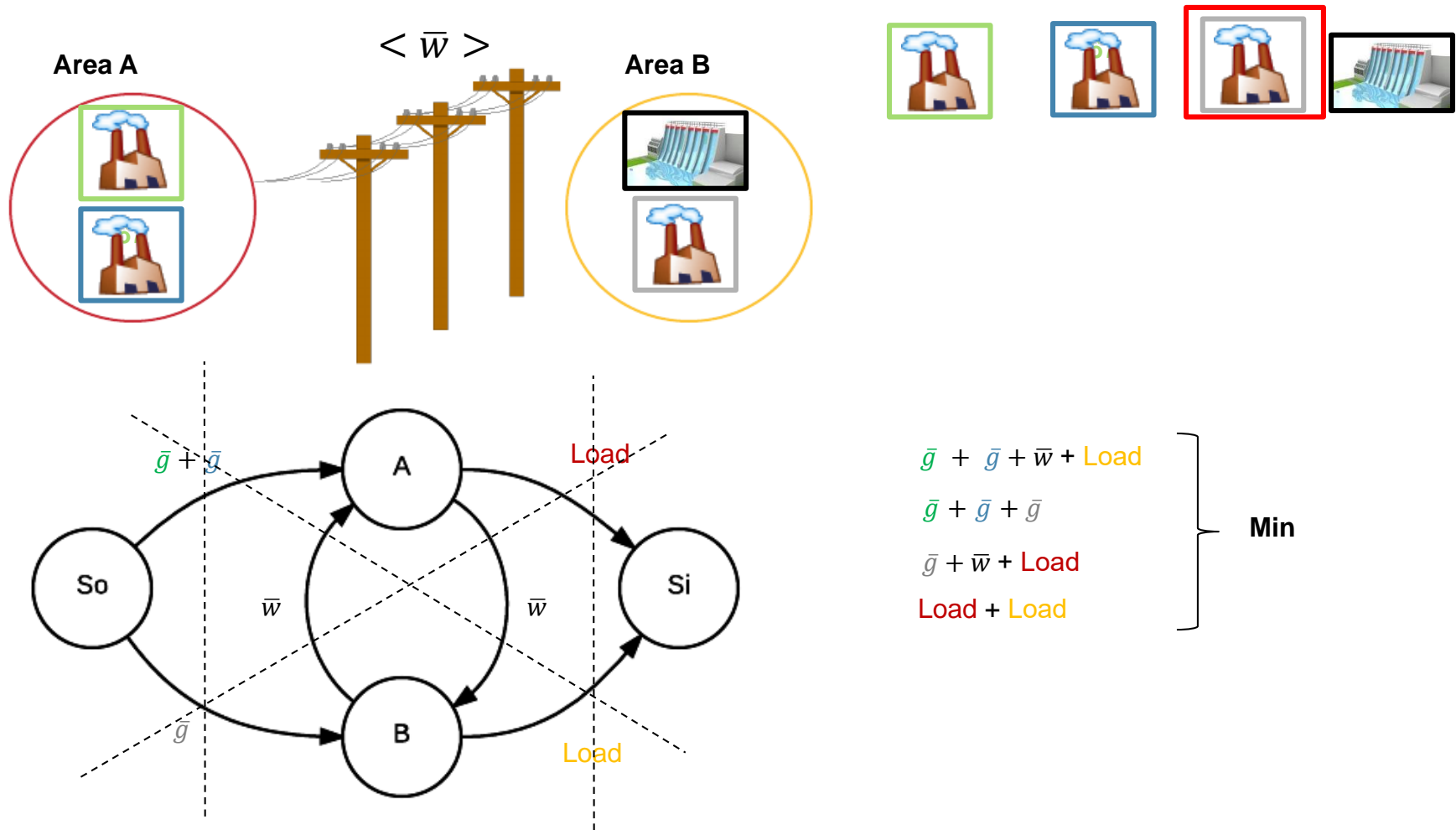
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



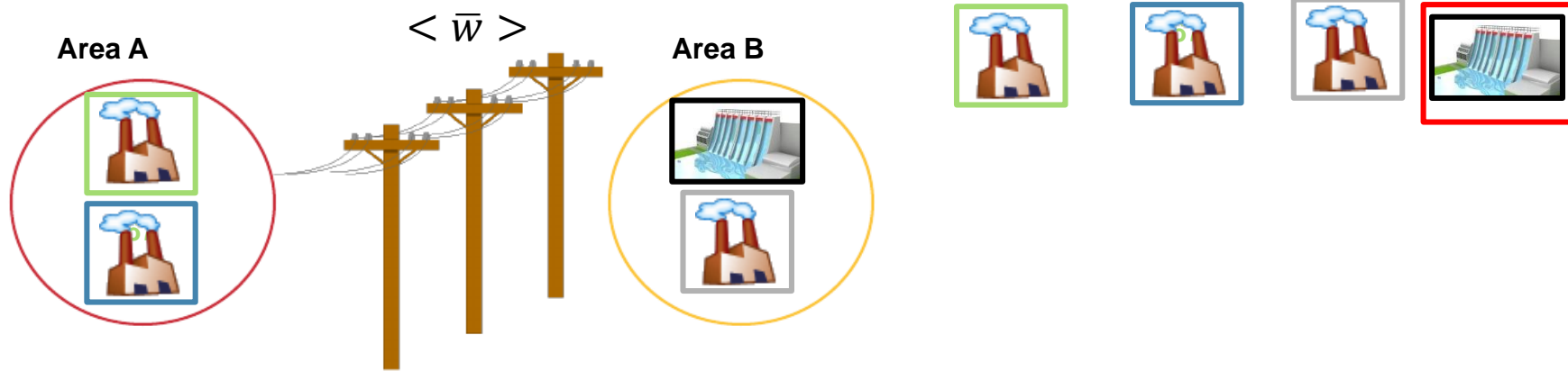
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



# Immediate cost function calculation method

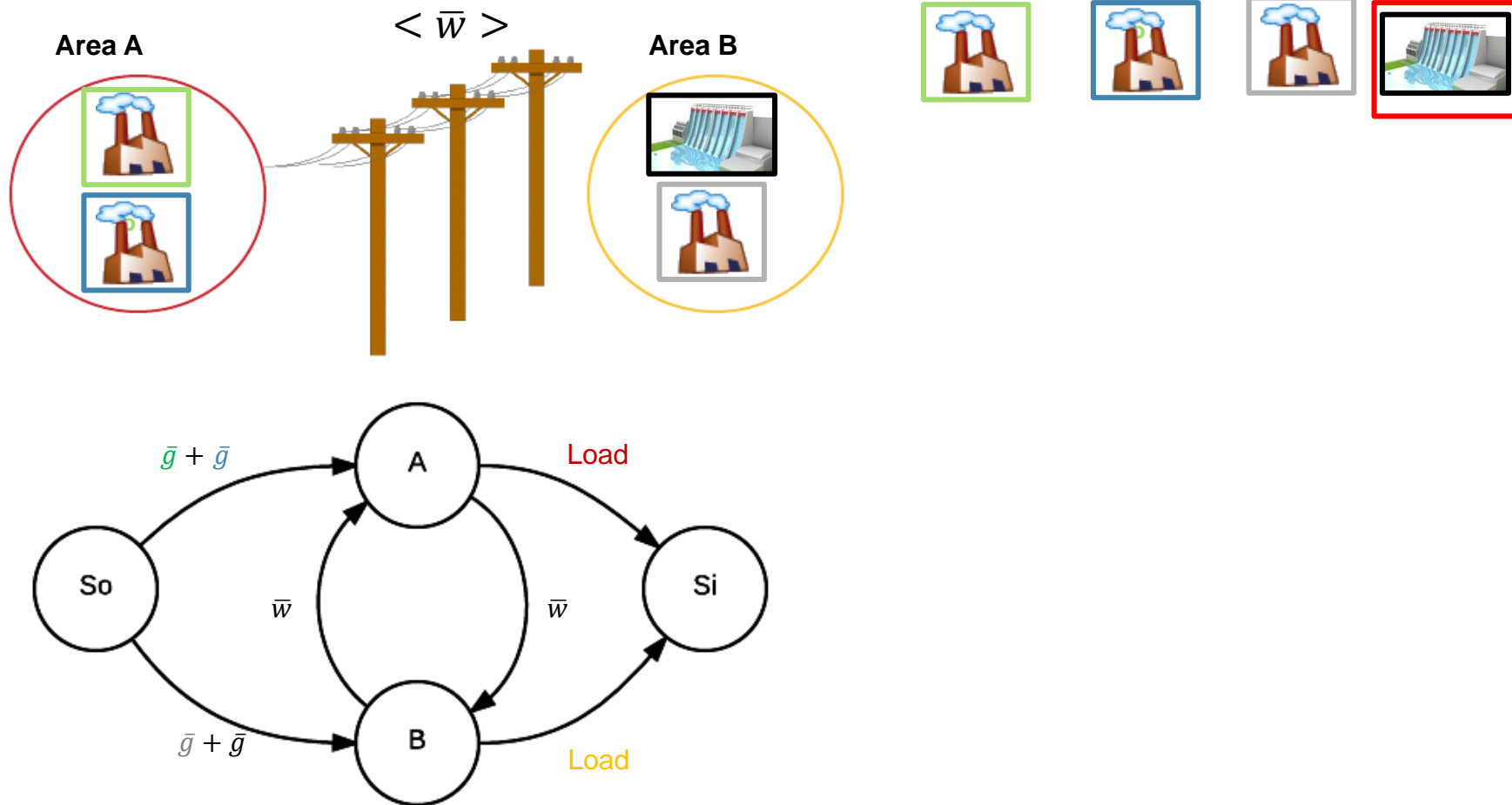
- In multi-area systems, we need to use min cut approach:





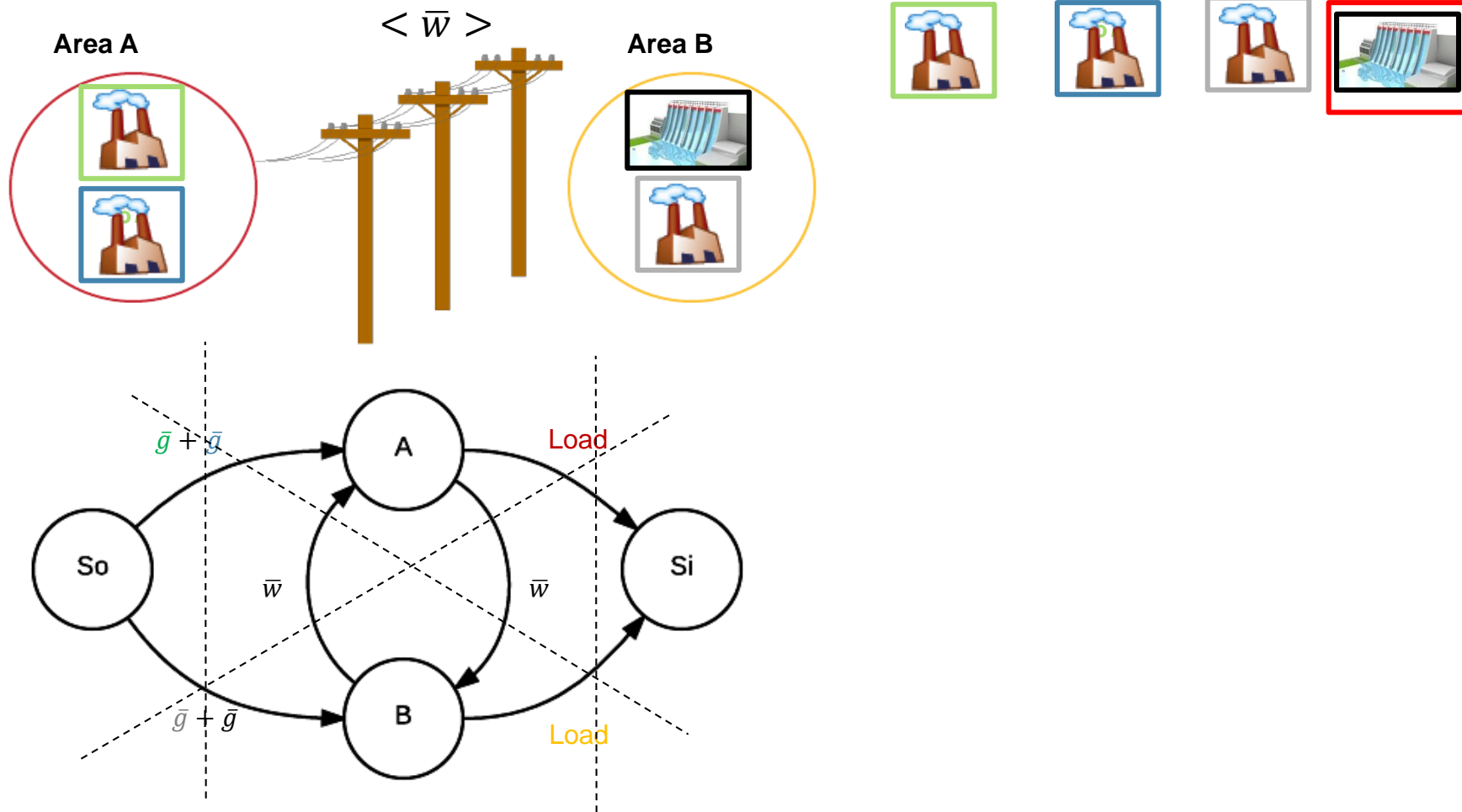
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



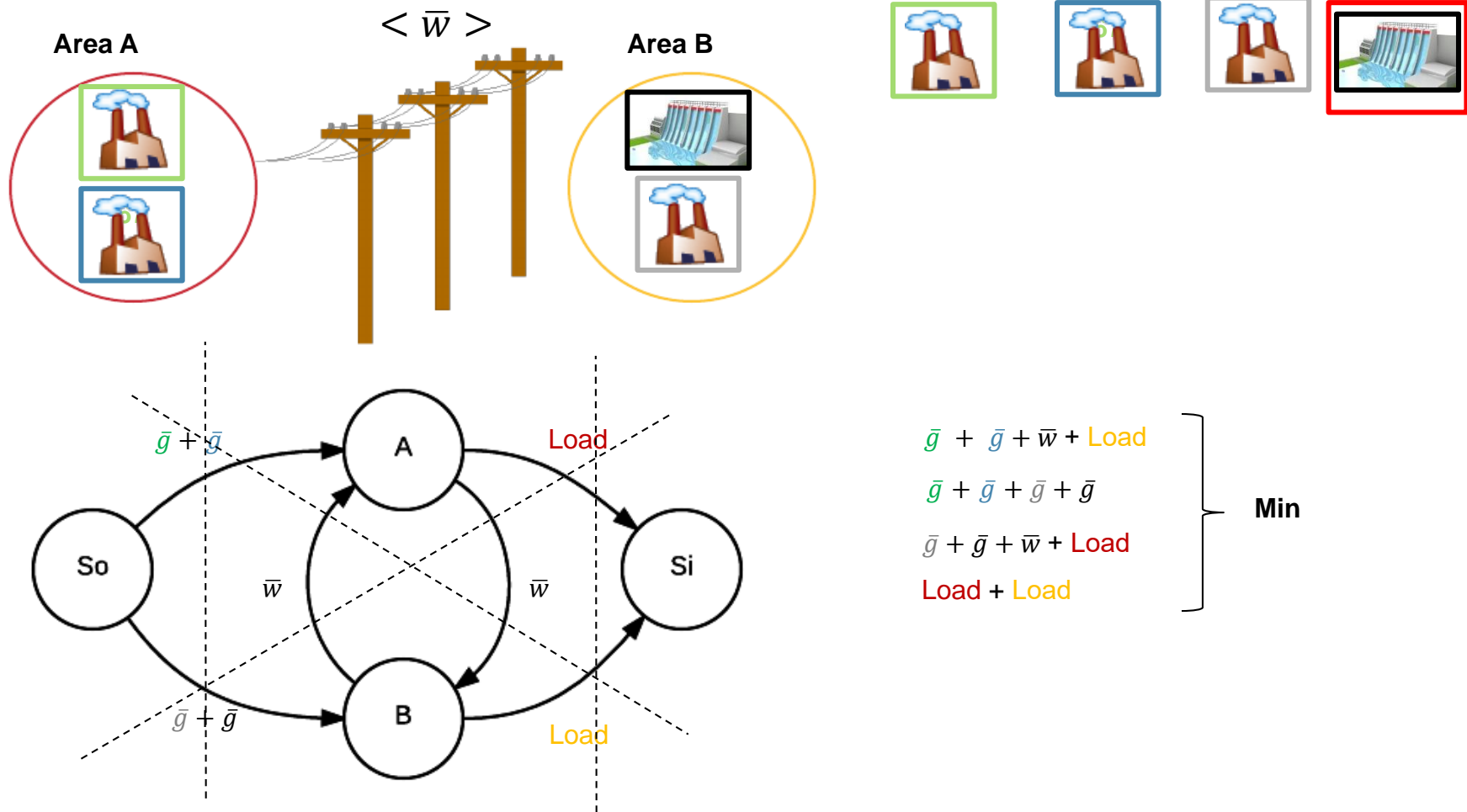
# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



# Immediate cost function calculation method

- In multi-area systems, we need to use min cut approach:



# Immediate cost function calculation method

---

- ▶ Immediate cost function calculations can be performed BEFORE SDDP execution, in parallel
- ▶ Points are then transformed into plans and inserted in SDDP just as FCF cuts.

# Outline

---

- ▶ Introduction
- ▶ SDDP
- ▶ Basic concepts
- ▶ Immediate cost function calculation method
- ▶ **Results**
- ▶ Final conclusions

# Results

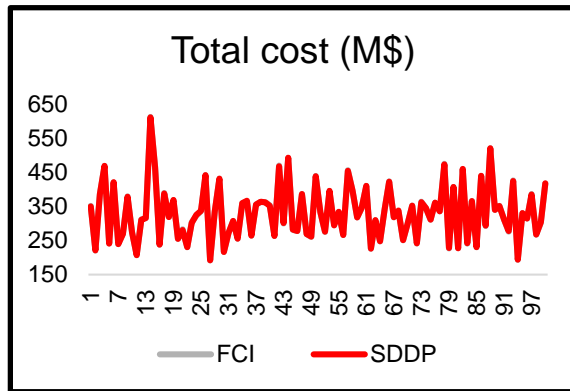
---

- ▶ Panama, Costa Rica & Nicaragua
- ▶ SDDP simulation performed using immediate cost approach and hourly resolution

# Results

- ▶ Panama, Costa Rica & Nicaragua
- ▶ SDDP simulation performed using immediate cost approach and hourly resolution

## Panama

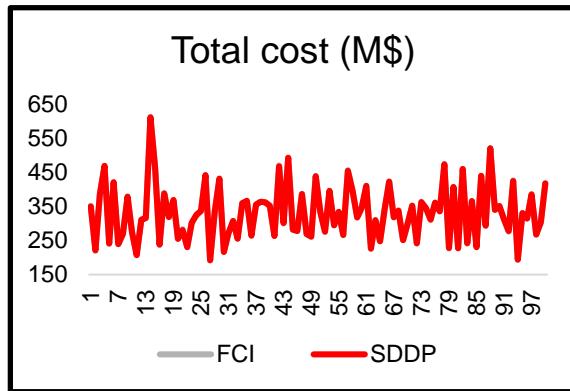


100 forward scenarios  
42 hydroelectric plants  
22 thermal plants

# Results

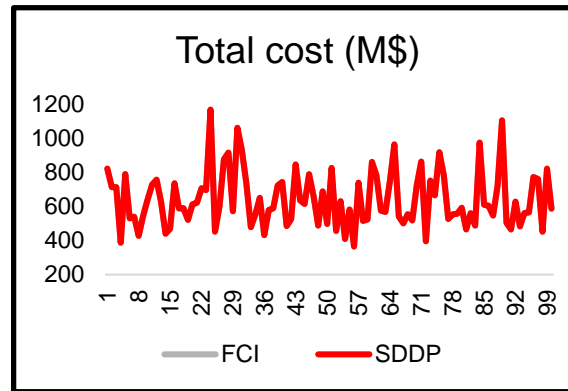
- ▶ Panama, Costa Rica & Nicaragua
- ▶ SDDP simulation performed using immediate cost approach and hourly resolution

**Panama**



100 forward scenarios  
42 hydroelectric plants  
22 thermal plants

**Panama & Costa Rica**



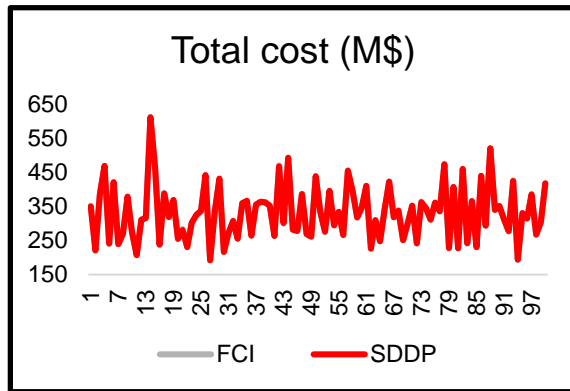
100 forward scenarios  
78 hydroelectric plants  
34 thermal plants



# Results

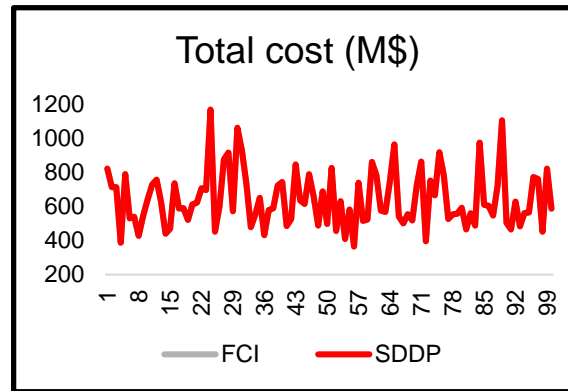
- Panama, Costa Rica & Nicaragua
- SDDP simulation performed using immediate cost approach and hourly resolution

Panama



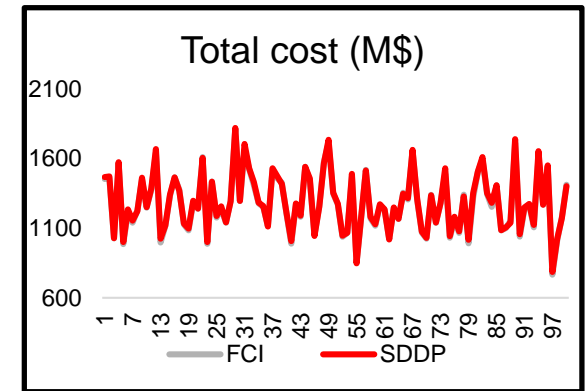
100 forward scenarios  
42 hydroelectric plants  
22 thermal plants

Panama & Costa Rica



100 forward scenarios  
78 hydroelectric plants  
34 thermal plants

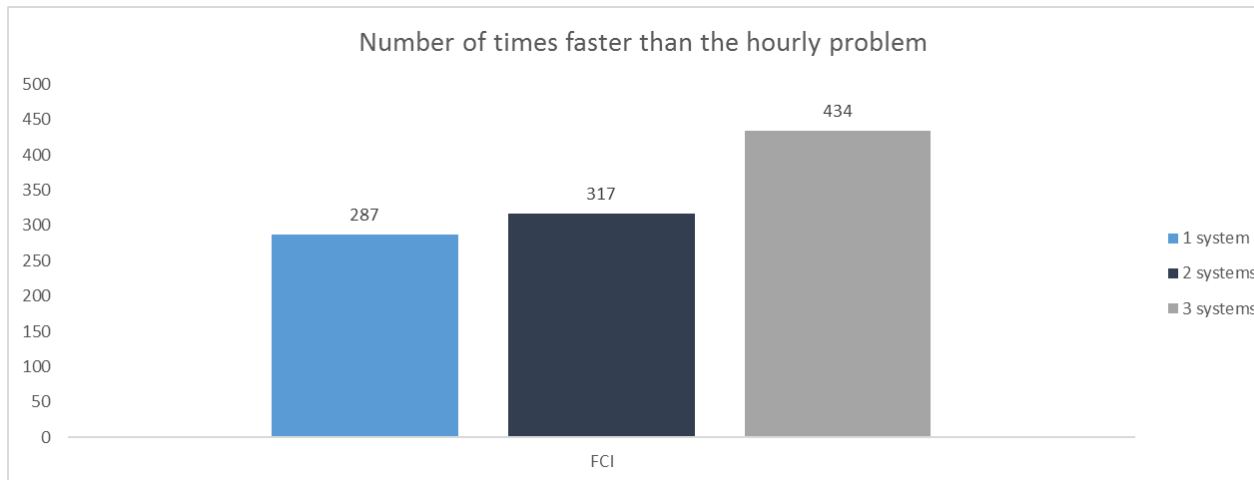
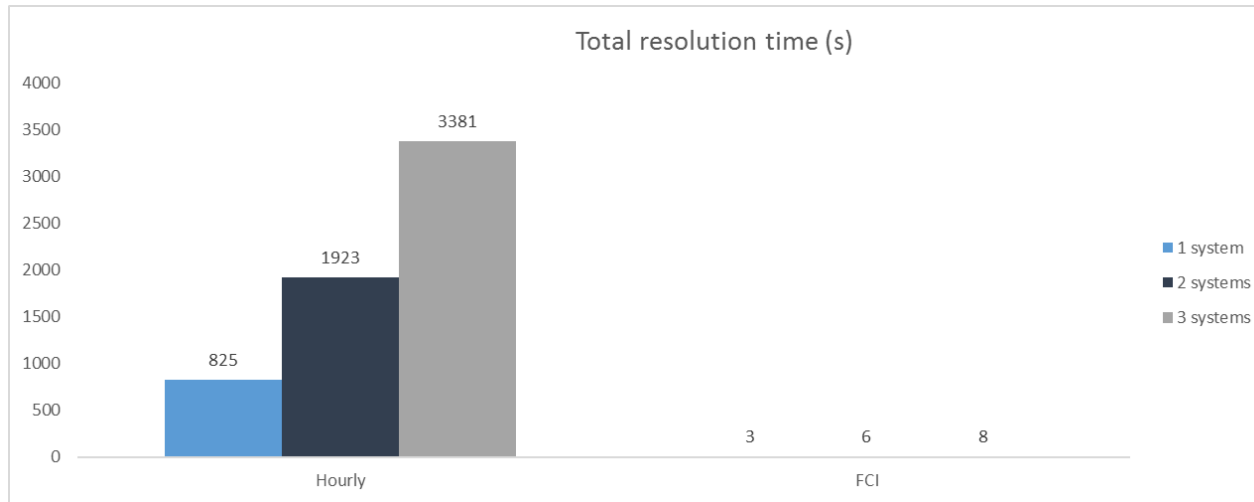
Panama, Costa Rica & Nicaragua



100 forward scenarios  
83 hydroelectric plants  
60 thermal plants

# Results

## ► Panama & Costa Rica & Nicaragua



# Outline

---

- ▶ Introduction
- ▶ SDDP
- ▶ Basic concepts
- ▶ Immediate cost function calculation method
- ▶ Results
- ▶ **Final conclusions**

# Final conclusions

---

- ▶ Renewable generation variability demands hourly representation, which is time consuming in current SDDP
- ▶ The methodology enables the obtainment of costs based on hourly results without representing hourly variables
- ▶ SDDP execution time using this approach is close execution time using block representation
- ▶ The approach can also be used to represent batteries and run-of-river plants. In this case, we would use interconnected hourly graphs to represent intra-stage time dependence

# PSR

**THANK  
YOU**

